The Diagnosis of Event Timing System in SuperKEKB Linac

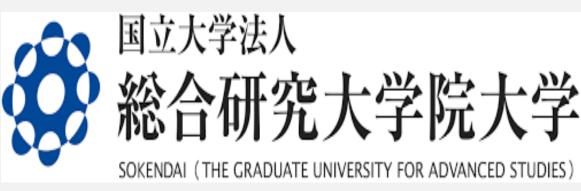
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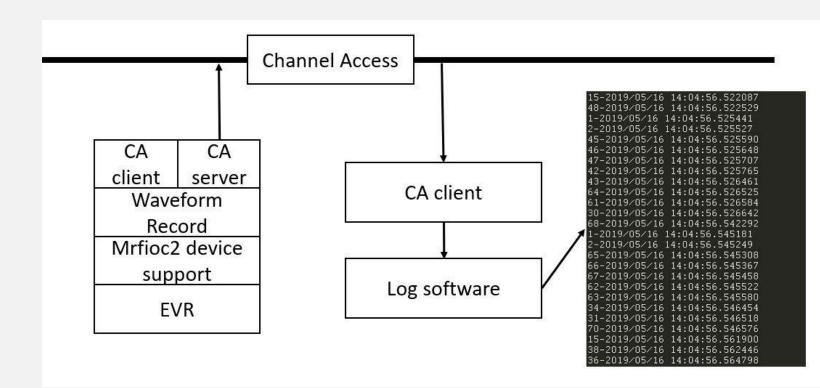
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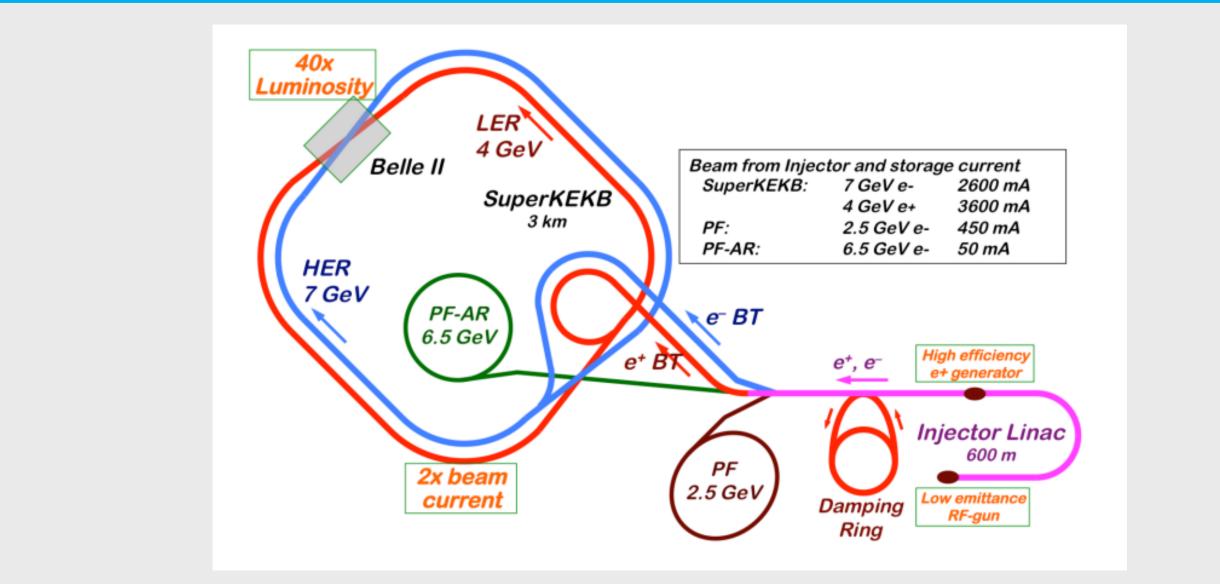
Introduction

We introduced MRF event timing system in injector linac in SuperKEKB to satisfy our demands. The event timing system is utilized to distribute high-level precise timing signals and accompanying control instructions to synchronize different subsystems and machines. EVG generates beam pulse pattern 50Hz which contains several event codes while EVR receives them. The Event rate is 114.24 MHz thus the minimal event time interval is about 9 ns. To certain that events are consistent between EVG and EVR, recording them one by one is essentially needed. Owing to some hardware and network restrictions it is difficult to continuously send every event by EVR through EPICS Chanel Access. An EVR based events diagnostic system is thus developed by modifying the device support of some records as well as EVR driver mrfioc2 to send the event codes thus comparing the received event codes with the beam-pattern control orders from beam operation and detecting the event timing interval fault as well as providing a logging system of persistent event data. Then, we are able to locate the fault, analyze the data, fix bugs or replace hardware and resume accelerator operation quickly.



- 32-bit wide FIFO memory (8-bit event code and 24-bit timestamp).
- EPICS 3.15.5
- VxWorks 6.8
- More than 300 records
- Self-defined waveform record, updated every 5 seconds

Event Based Timing Control System



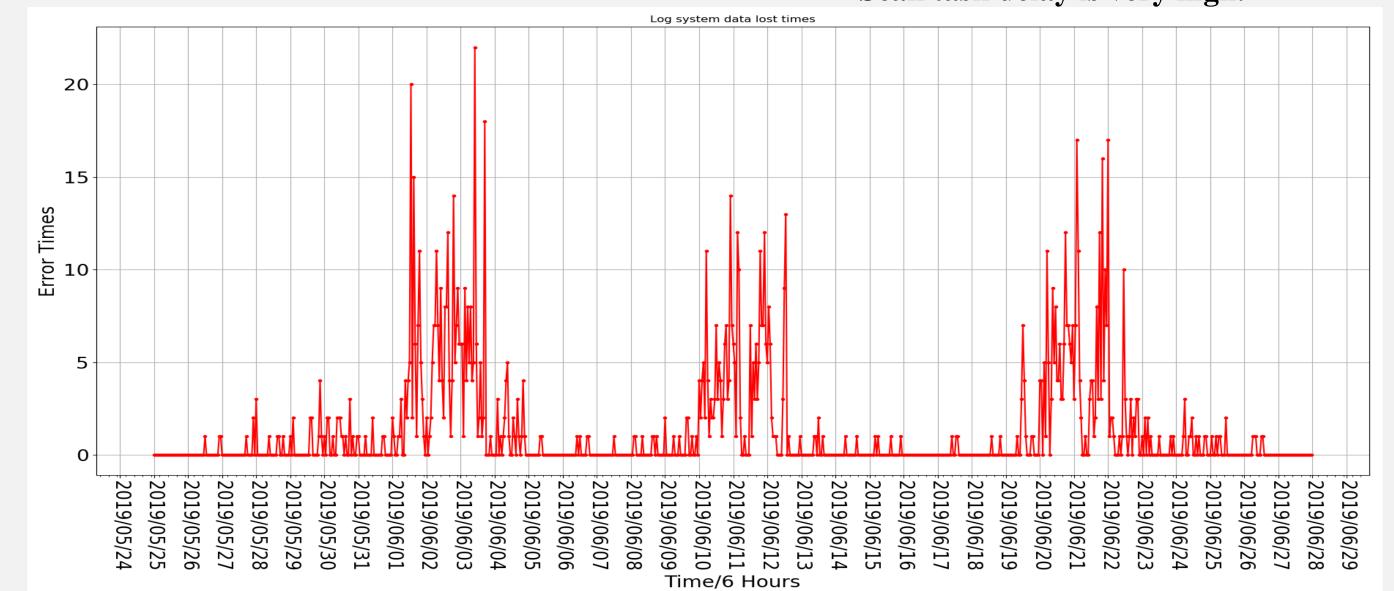
- MVME5500 CPU frequency is 1 GHz, by contrast, the minimal interval between linac event code is 9 ns.
- VxWorks clock tick is 1000
- i.e. scan-5 task delay is 4.579 second.

CPU burden is too heavy !

Python 3.7 CA Client (pyepics-3.3.3)

| NAME | ENTRY | TID | PRI | STATUS | PC | SP | ERRNO | DELAY |
|-------------|--------------|----------|-----|--------|--------|----------|--------|--------|
| tJobTask | 1ce564 | 4db1d0 | 0 | PEND | 24ec6c | 4db0f0 | 0 | 0 |
| tExcTask | 1cd904 | 302970 | 0 | PEND | 24ec6c | 302870 | 0 | 0 |
| tLogTask | logTask | 4de570 | 0 | PEND | 24ce28 | 4de430 | 0 | 0 |
| tNbioLog | 1cf238 | 4e1ea0 | 0 | PEND | 24ec6c | 4e1d80 | 0 | 0 |
| tShell0 | shellTask | 5f7d60 | 1 | PEND | 24ec6c | 5f7a30 | 0 | 0 |
| tShellRem6> | | 614790 | | READY | 257338 | 612990 | ad0007 | 0 |
| ipcom_tick> | | 566410 | 20 | DELAY | 25615c | | 0 | 91 |
| tNet0 | ipcomNetTask | | 50 | READY | 24ec6c | 4e6eb0 | 3d0001 | 0 |
| ipcom_sysl> | 17af48 | 5a2670 | 50 | PEND | 24f588 | 5a24c0 | 0 | 0 |
| | ipcom_telnet | 5dcb70 | 50 | PEND | 24ec6c | 5dc970 | 0 | 0 |
| ipsntps | 1bab80 | 5dfd60 | 50 | PEND+T | 24ec6c | 5dfbe0 | 3d0004 | 519514 |
| ipcom_teln> | ipcom_telnet | 1fffda80 | 50 | PEND | 24ec6c | 1fffd860 | 0 | 0 |
| tStdioProx> | 18186c | 1ffff4b0 | 50 | READY | 24ea64 | 1fffefb0 | 0 | 0 |
| tLogin1fff> | 181af0 | 6034c0 | 50 | PEND | 24f588 | 6033f0 | 0 | 0 |
| tPortmapd | portmapd | 5e3d10 | 54 | PEND | 24ec6c | 5e3ac0 | 16 | 0 |
| EVRFIFO | af4d00 | 634Ъ60 | | READY | 24ce28 | 634980 | 0 | 0 |
| EVRFIFO | af4d00 | c00ed0 | | | 24ce28 | c00cf0 | 0 | 0 |
| cbHigh | af4d00 | 74с7ЬО | | | 24ec6c | | 0 | 0 |
| timerQueue | af4d00 | 6f73b0 | | | 24ec6c | | 3d0004 | 0 |
| scanOnce | af4d00 | 7df930 | | | 24ec6c | | 0 | 0 |
| scan-0.1 | af4d00 | | | PEND+T | 24ec6c | | 3d0004 | 28 |
| scan-0.2 | af4d00 | | | PEND+T | 24ec6c | | 3d0004 | 128 |
| cbMedium | af4d00 | 743f90 | | | 24ec6c | | 0 | 0 |
| scan-0.5 | af4d00 | | | PEND+T | 24ec6c | | 3d0004 | |
| scan-1 | af4d00 | 7fb0f0 | | PEND+T | 24ec6c | | 3d0004 | 80 |
| scan-2 | af4d00 | 7f45d0 | | | 24ec6c | 7f4410 | 3d0004 | 1579 |
| scan-5 | af4d00 | | | PEND+T | 24ec6c | 7ed8f0 | 3d0004 | 4579 |
| scan-10 | af4d00 | 7e6f90 | 139 | PEND+T | 24ec6c | 7e6dd0 | 3d0004 | 9579 |

Scan task delay is very high.

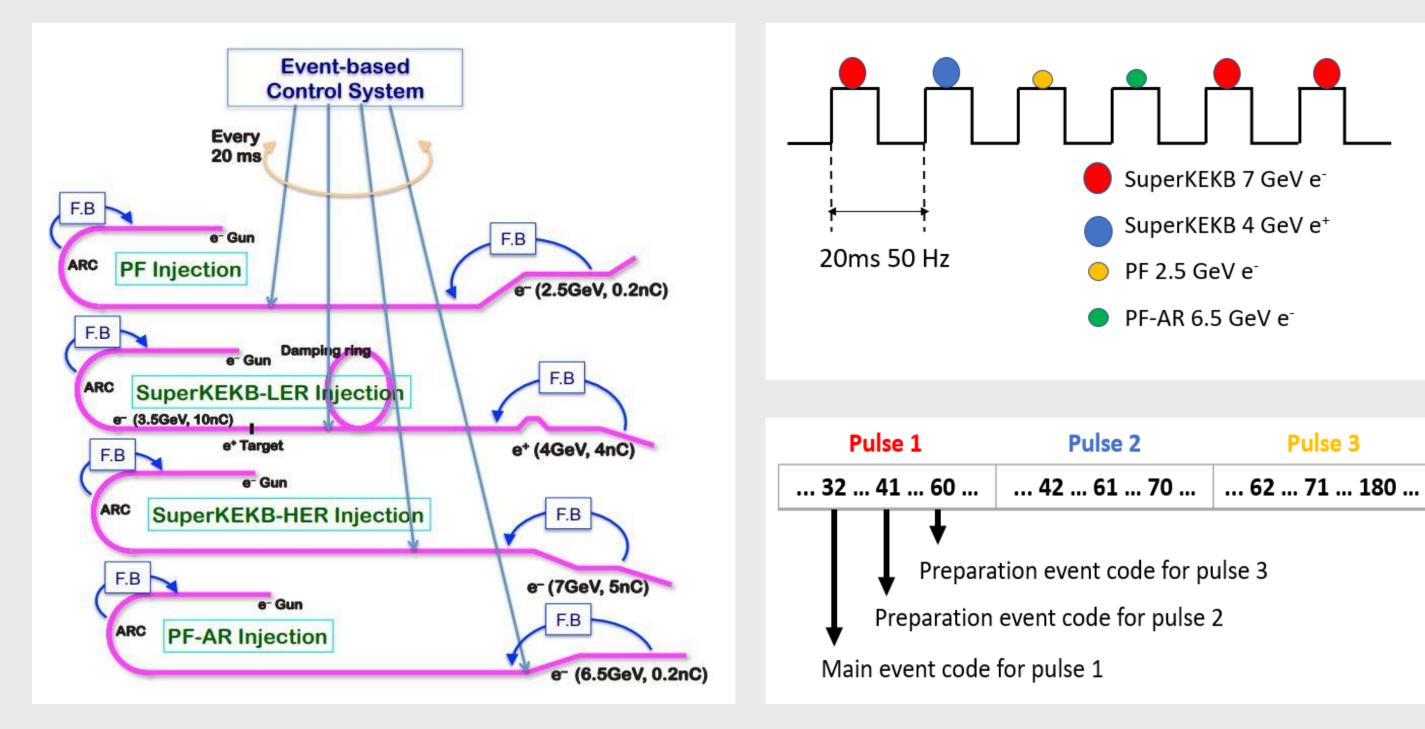


Event Log System

Waveform data lost about 1000 times in one month owing to scan task delay

upgrade

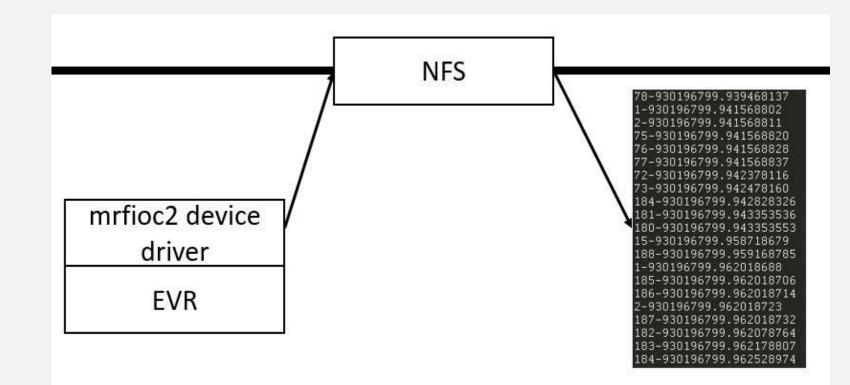
SuperKEKB Accelerator



- Simultaneous top-up injection for 5 independent rings.
- Pulse-to-Pulse Modulation (PPM) every 20 ms (2 ms width of fluctuation).
- (SKB e-/e+, e+ damping ring, PF, PF-AR) w/ different beam energies.
- Beam pattern buffer length can be 2 to 500 (40 ms to 10 seconds).
- More than <u>10 events</u> are transferred every pulse.



Low-level system

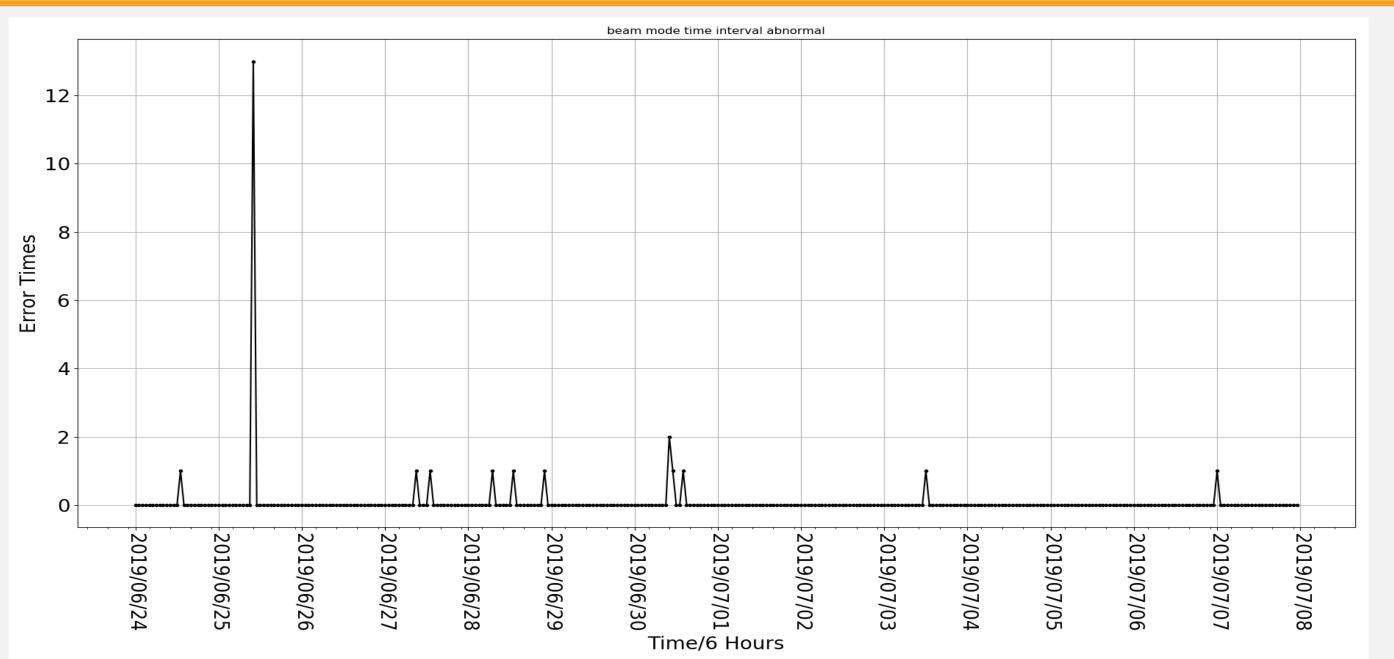


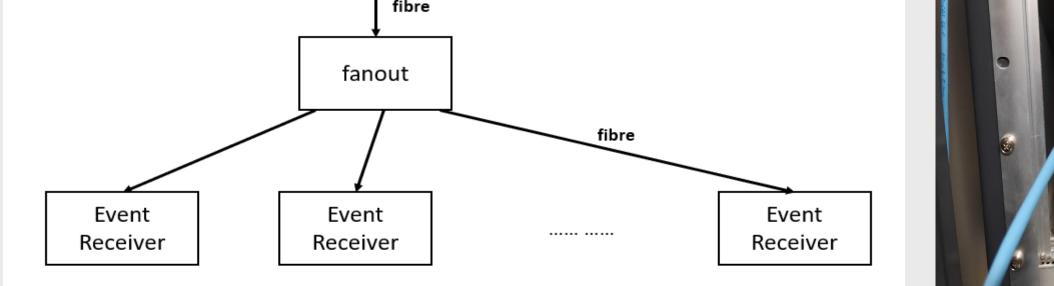
No log system data lost error occurs !

• Lower MVME CPU burden.

- Only some EVR configuration records and event code I/O interrupt records are retained.
- Mrfioc2 module is modified.
- Using binary format to transit event and timestamp
- About 429 MB data every day.
- Python analyzing program will check the log as well as sending email every day (using crontab)









- Event based system (EVG and EVR)
 - 256 Event codes, one event code/cycle (7 ns 20 ns or 50 MHz to 142 MHz)
- 114.24 MHz is used in SuperKEKB Linac.
- Event stream based on 8B10B encoding
- Abnormal beam pulse interval was noticed during operation occasionally.
- Some devices like klystron will be triggered twice during 20 ms.
- Event log system is needed.

Abnormal beam mode interval information.

Outlook

In the near future, after the SuperKEKB injector linac operate on October, much more event code data will be saved and analyzed. Subsequently, we hope to utilize some the feature extraction algorithm to figure out the reason of abnormal beam mode intervals with the help of these event code timestamp information.