



Performance of the cERL LLRF System

Compact ERL (Energy Recovery LINAC)



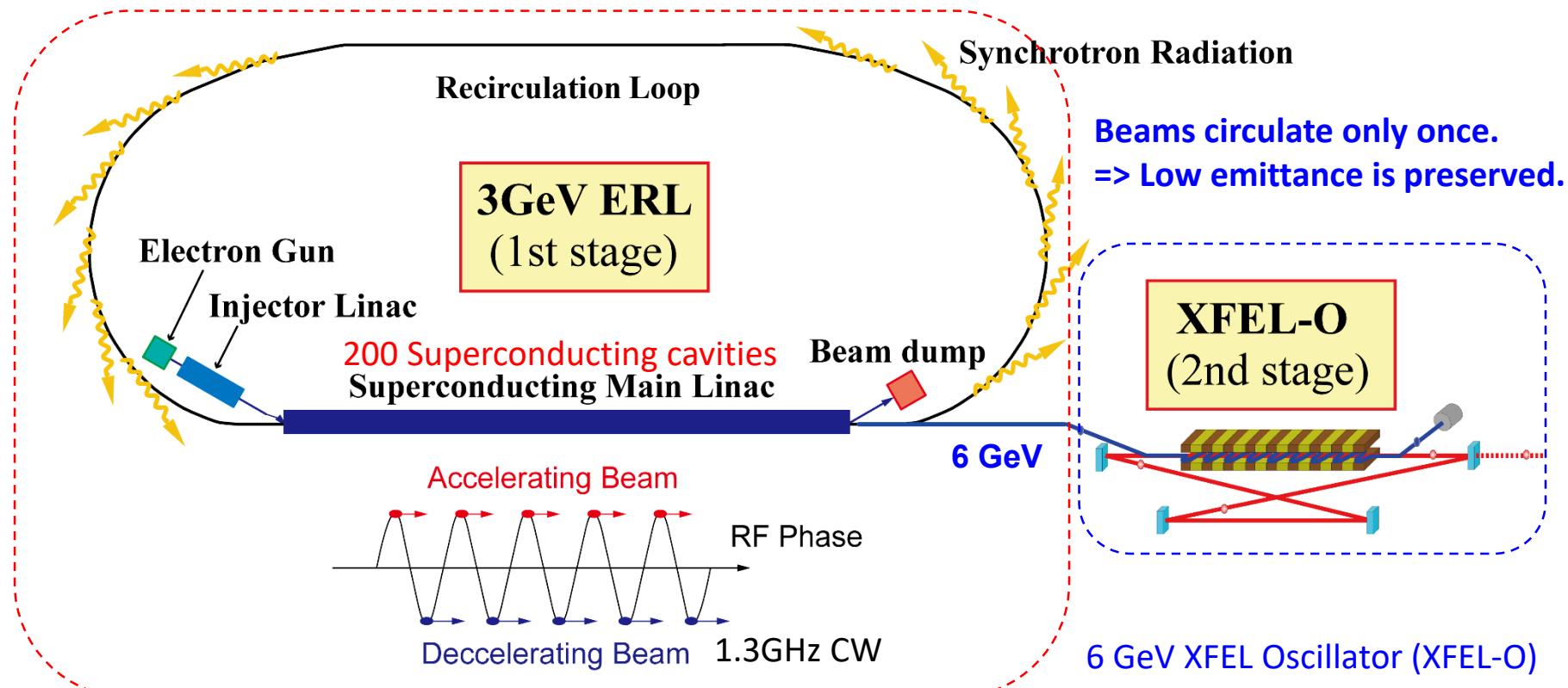
Takako Miura (KEK)



Future Plan of 3GeV ERL Light Source at KEK



- [1] **3GeV ERL as VUV and X-ray SR source** (high flux and short pulse)
(10 mA – 100 mA, ϵ_n : 0.1 mm·mrad, bunch length:100fs@min)
- [2] **6GeV XFEL Oscillator** (2 times acceleration by 2 circulations)

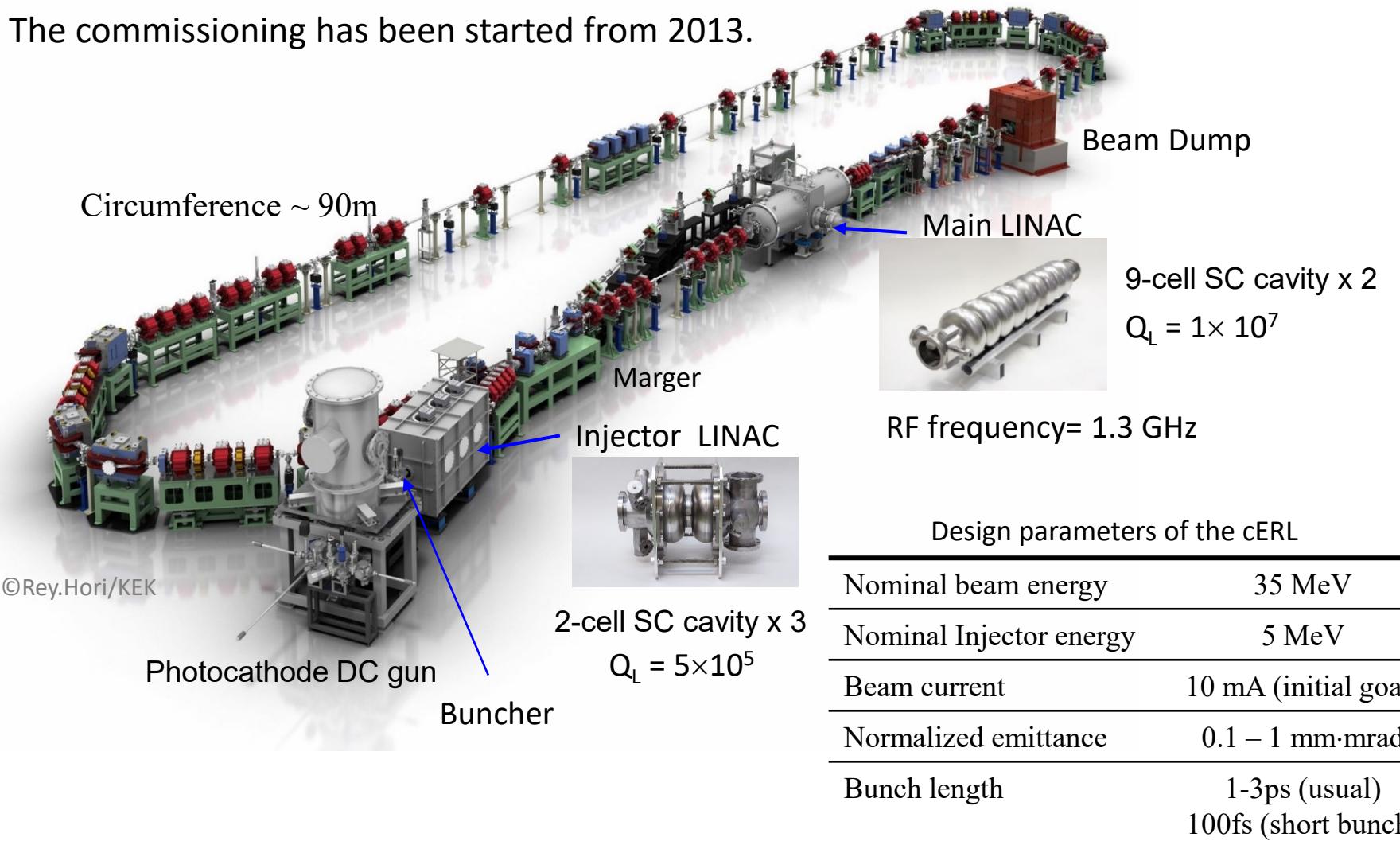




Introduction of cERL

Compact ERL (cERL) has been constructed as a test facility of a **3-GeV ERL** future plan.

The commissioning has been started from 2013.





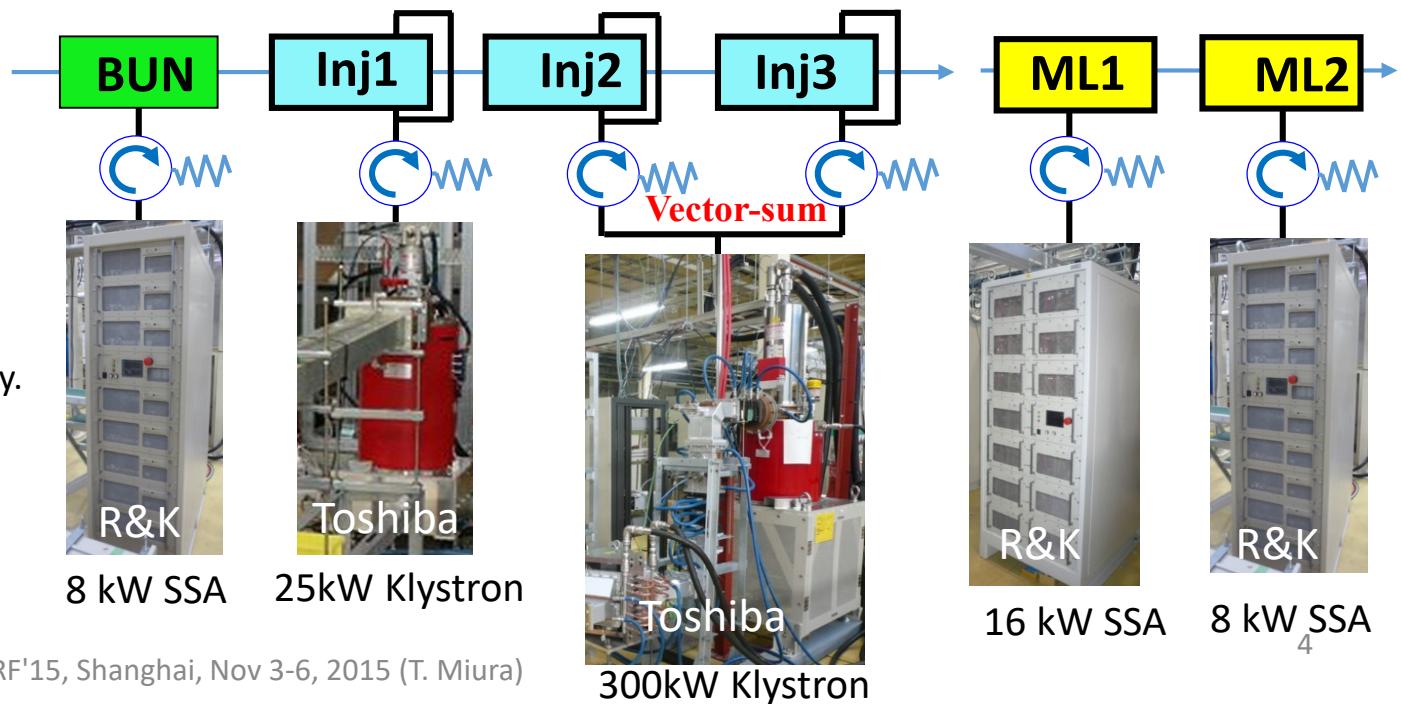
Current status of high power RF sources

	Buncher	Inj-1	Inj-2	Inj-3	ML-1	ML-2
Cavity	NC	2cell-SC	2cell-SC	2cell-SC	9cell-SC	9cell-SC
Cavity Voltage	114 kV	0.7 MV	0.7 MV	0.7 MV	8.6 MV	8.6 MV
Field Gradient (Desgin)		3 MV/m (7.5MV/m)	3MV/m (7.5MV/m)	3MV/m (7.5 MV/m)	8.6 MV/m (15MV/m)	8.6 MV/m (15MV/m)
Q_L	1.1×10^5	1.2×10^6	5.8×10^5	4.8×10^5	1.3×10^7	1.0×10^7
Cavity Length	0.068 m	0.23 m	0.23 m	0.23 m	1.036 m	1.036 m
RF Power @Low beam current	3 kW	0.53 kW		2.6 kW	1.6 kW	2 kW

<Design>
100mA beam &
 $V_c = 2\text{MV}$ at Inj.Cav

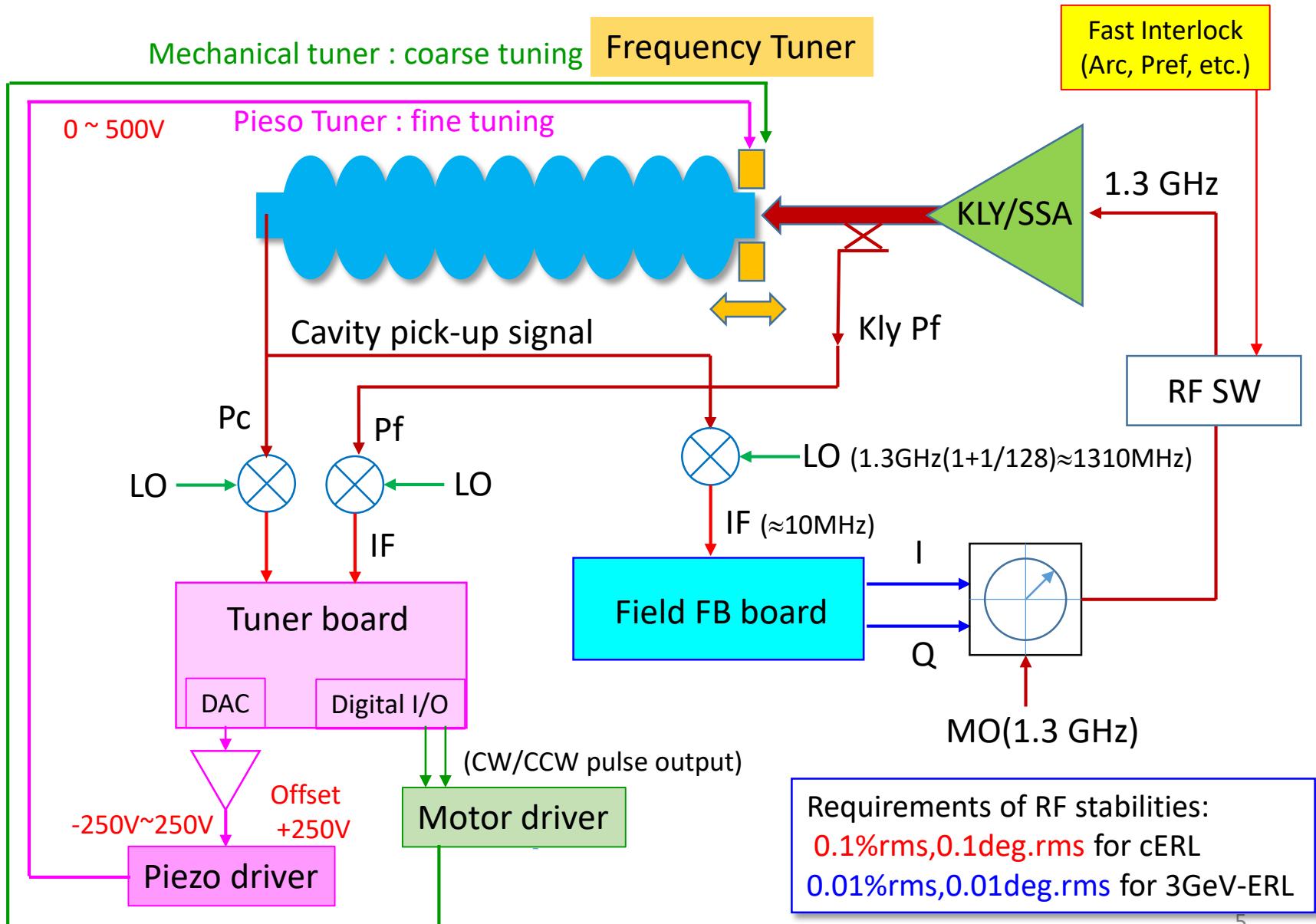


200kW RF power is
necessary for each inj. cavity.



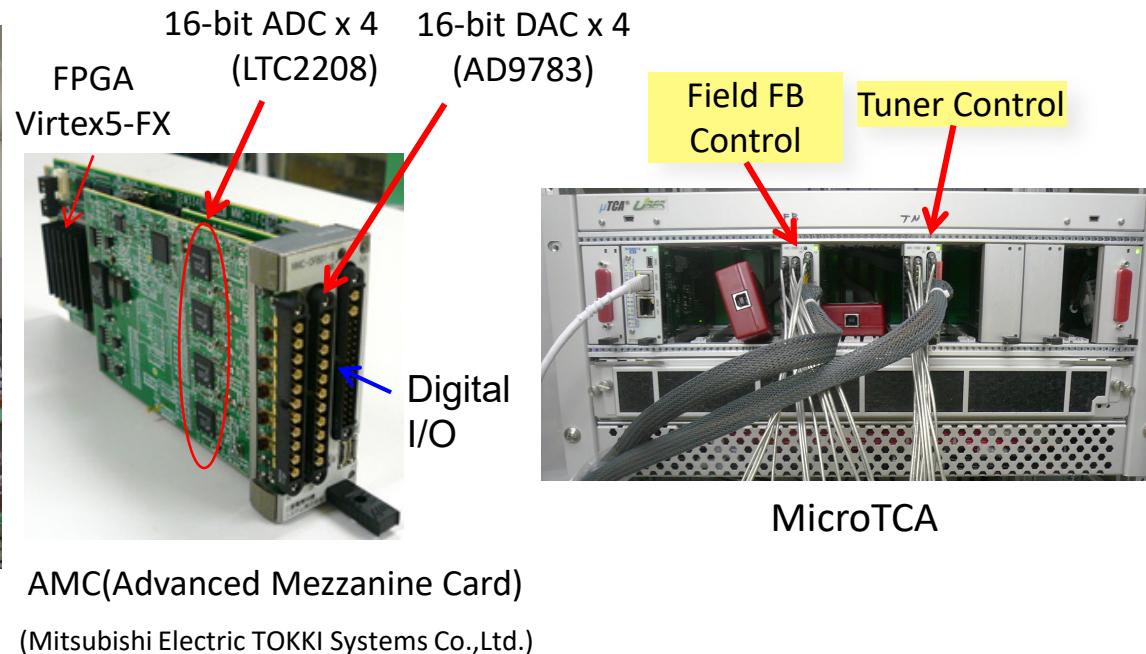


Digital LLRF System at cERL





Digital LLRF Boards



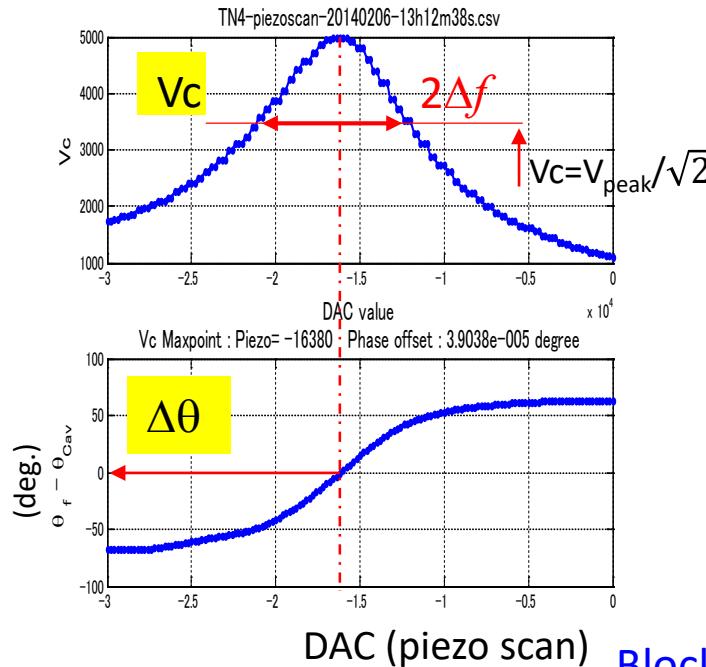
Total 11 boards are used for operation.

	BUN	Inj1	Inj2	Inj 3	ML1	ML2
RF FB board	FBO	FB1	FB2 (Vec-sum)	FB4	FB5	
Tuner board	TN0	TN1	TN2	TN3	TN4	TN5

- Embedded Linux is working in the PowerPC on FPGA.
- Each board acts as an **EPICS IOC**.
- Data acquisition is performed through **GbE bus** on the backplane.



Frequency Feedback Control



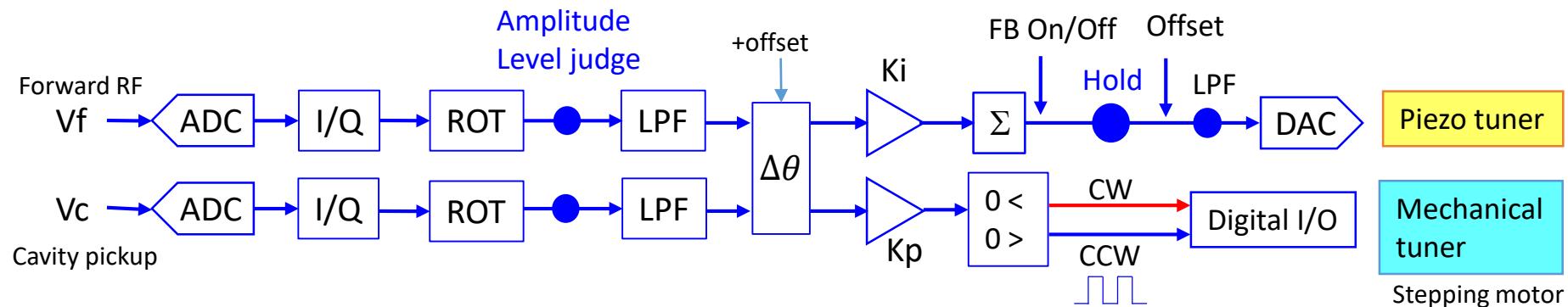
$\Delta f = 65 \text{ Hz}$ for ML cavities ($Q_L = 10^7$)
Narrow bandwidth for $f_0 = 1.3 \text{ GHz}$

$\Delta\theta = \theta_f - \theta_c$: The phase difference between the input RF and the cavity pickup signal

$$\tan\Delta\theta \approx 2Q_L \frac{\Delta f}{f}$$

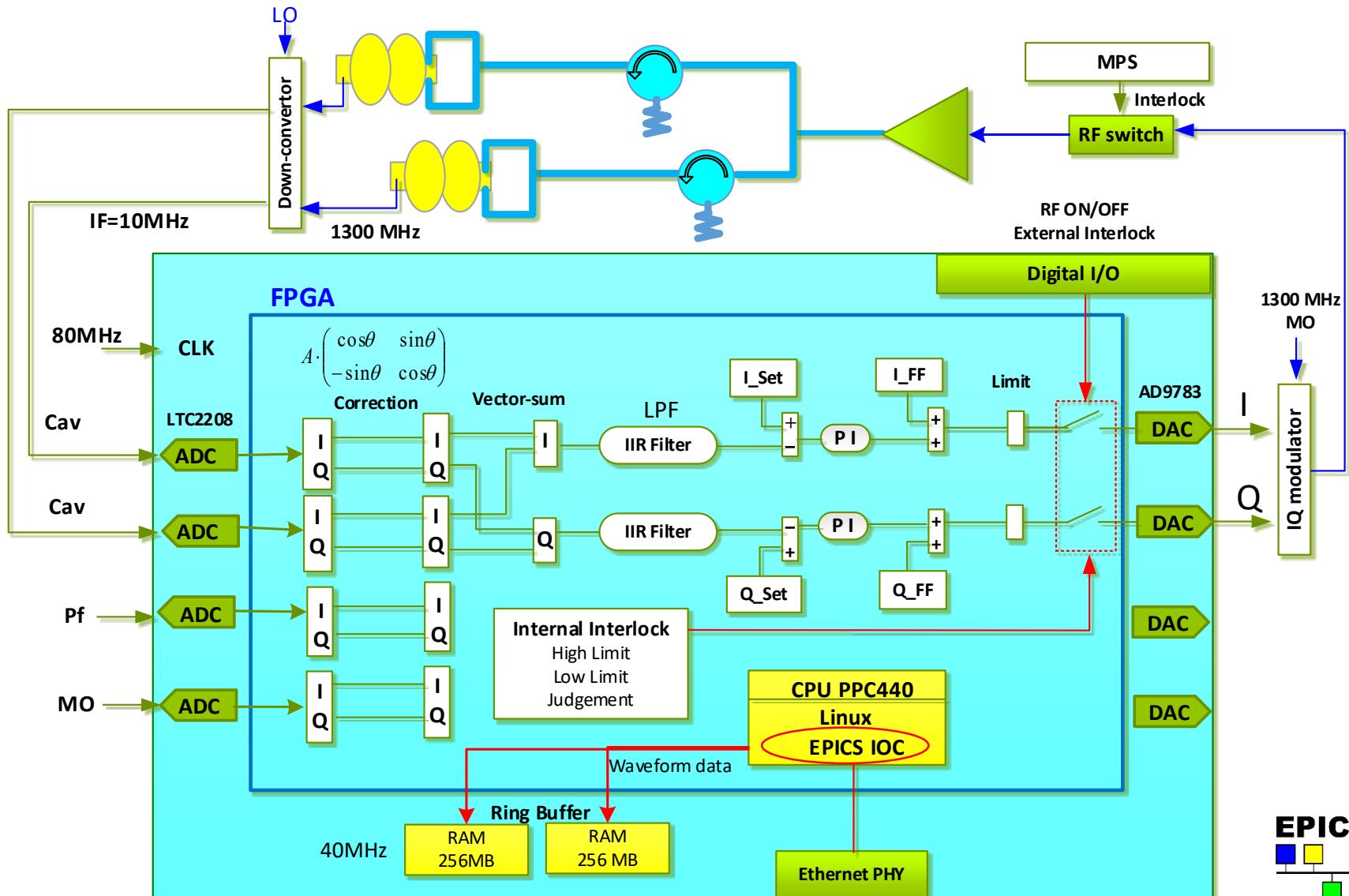
To keep resonance frequency,
tuner should be controlled to maintain $\Delta\theta$ at zero.

Block diagram of frequency FB control





Field Feedback Control



$$I = \frac{1}{4} \sum_{n=0}^7 \cos\left(2\pi \frac{n}{8}\right) \cdot V(n), Q = \frac{1}{4} \sum_{n=0}^7 \sin\left(2\pi \frac{n}{8}\right) \cdot V(n)$$

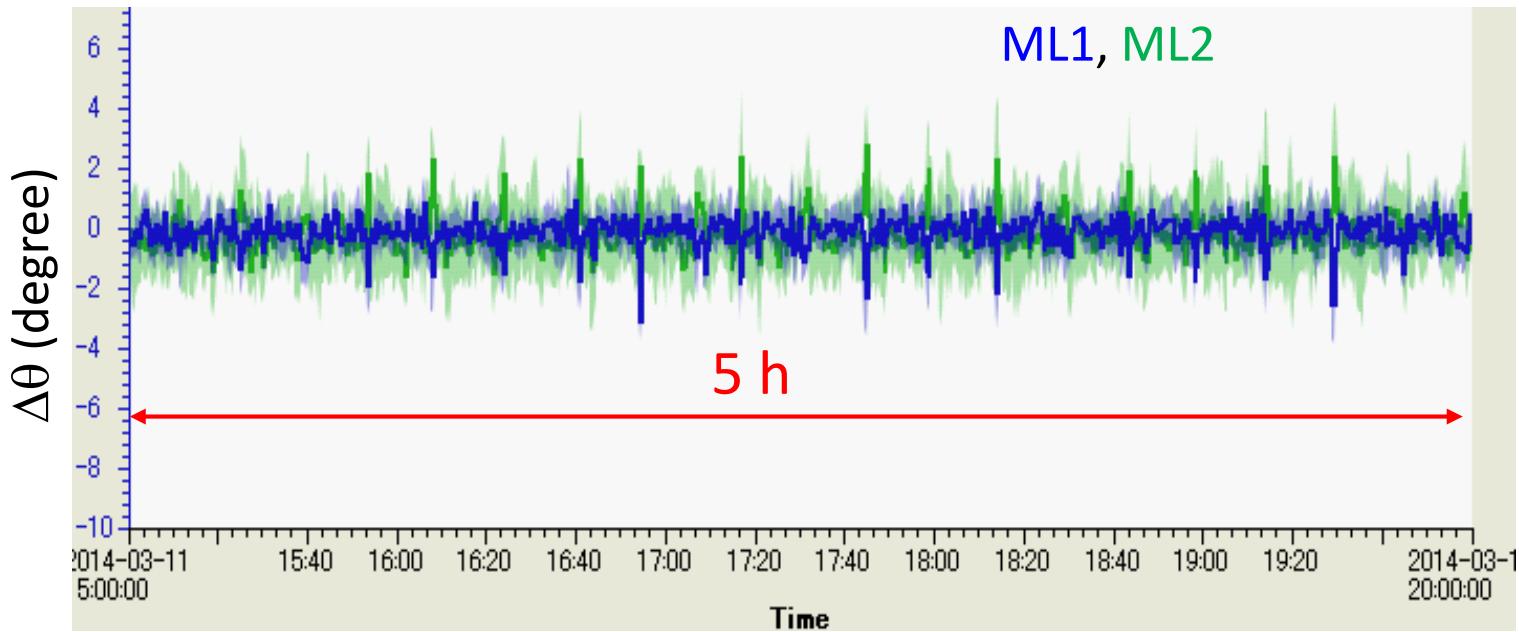
Wave Forms
Parameter set

EPICS is used for control communication.
8



Results of Frequency Control

$$\Delta\theta = \theta_f - \theta_c$$



$$\tan\Delta\theta \approx 2Q_L \frac{\Delta f}{f}$$

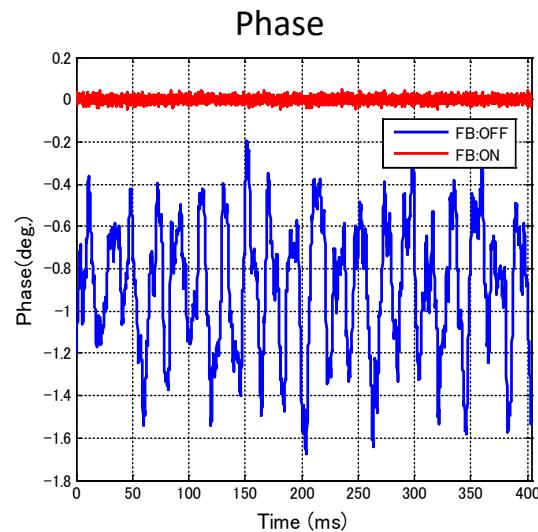
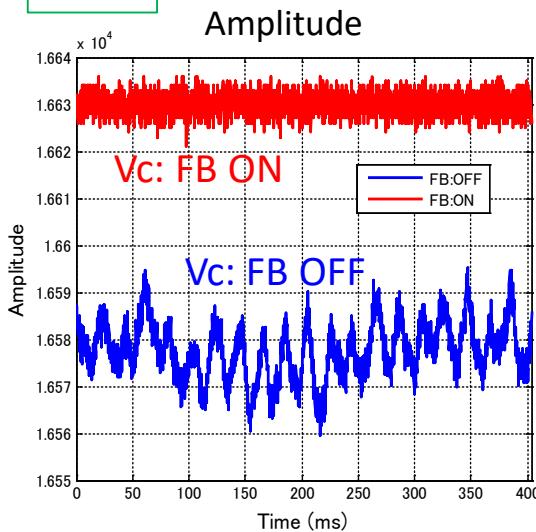
$$\Delta\theta = \pm 3\text{deg.} \quad Q_L \approx 10^7 \Rightarrow \Delta f \approx \pm 3.4 \text{ Hz}$$



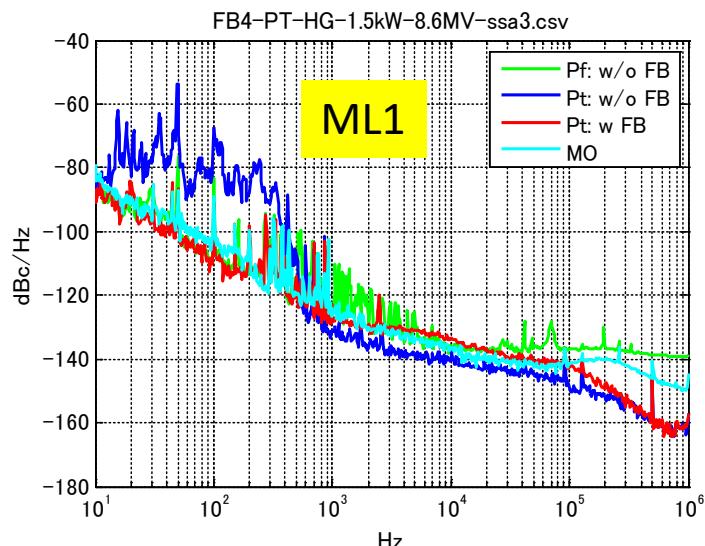
Performance of RF Feedback Control

ML1

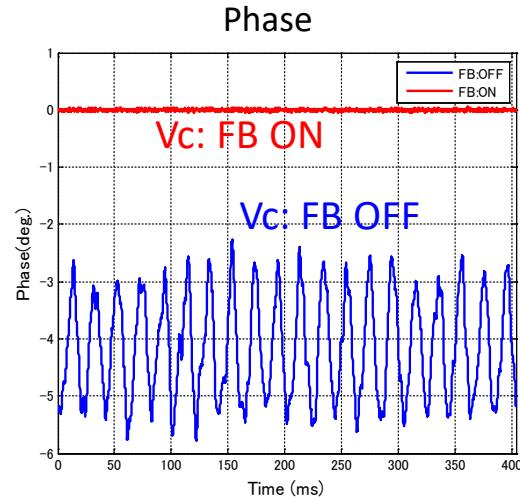
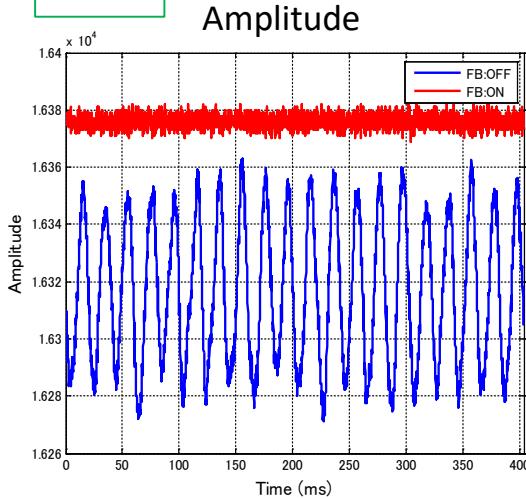
Waveforms of cavity pick-up



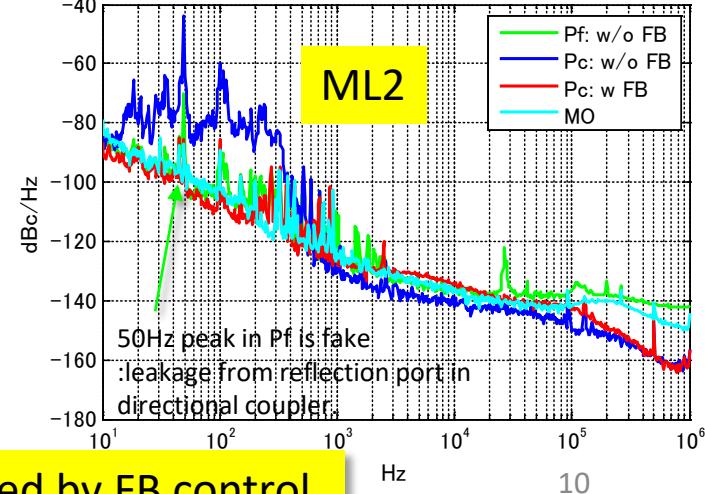
Phase noise measurement using signal source analyzer



ML2



FB5-PT-HGFB-1.5kW-8.6MV-ssa-20140521-2.csv



Fluctuations by microphonics have been well suppressed by FB control.



RF Stabilities

Monitored with IIR LPF(5kHz)

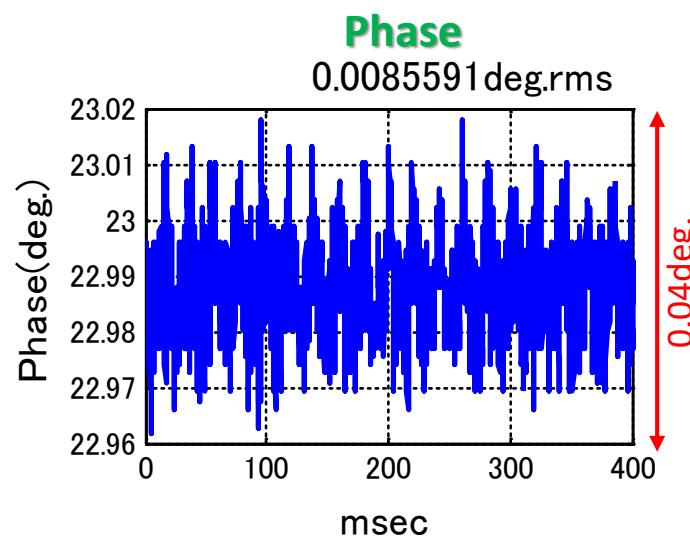
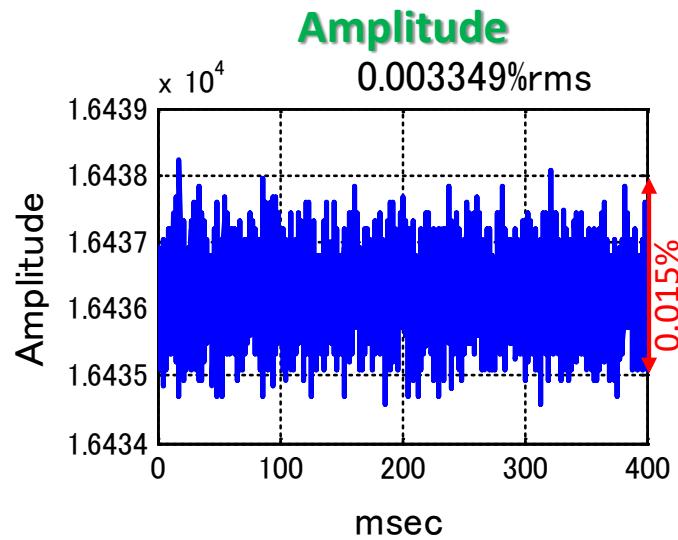
	Inj1	Inj2 & Inj3	ML1	ML2
Amplitude	0.006% rms	0.007% rms	0.003% rms	0.003% rms
Phase	0.009° rms	0.025° rms	0.010° rms	0.009° rms

Requirements:

0.1%rms, 0.1deg.rms for cERL

0.01%rms, 0.01deg.rms for 3GeV-ERL

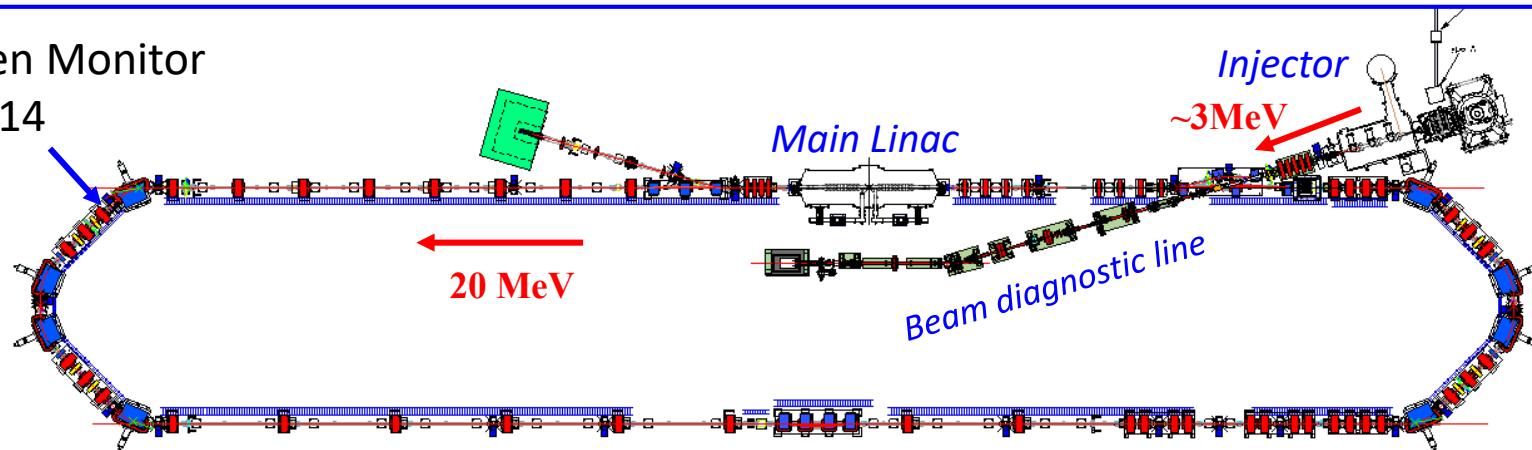
ML2





Stability of Beam Momentum (1)

Screen Monitor
CAM14



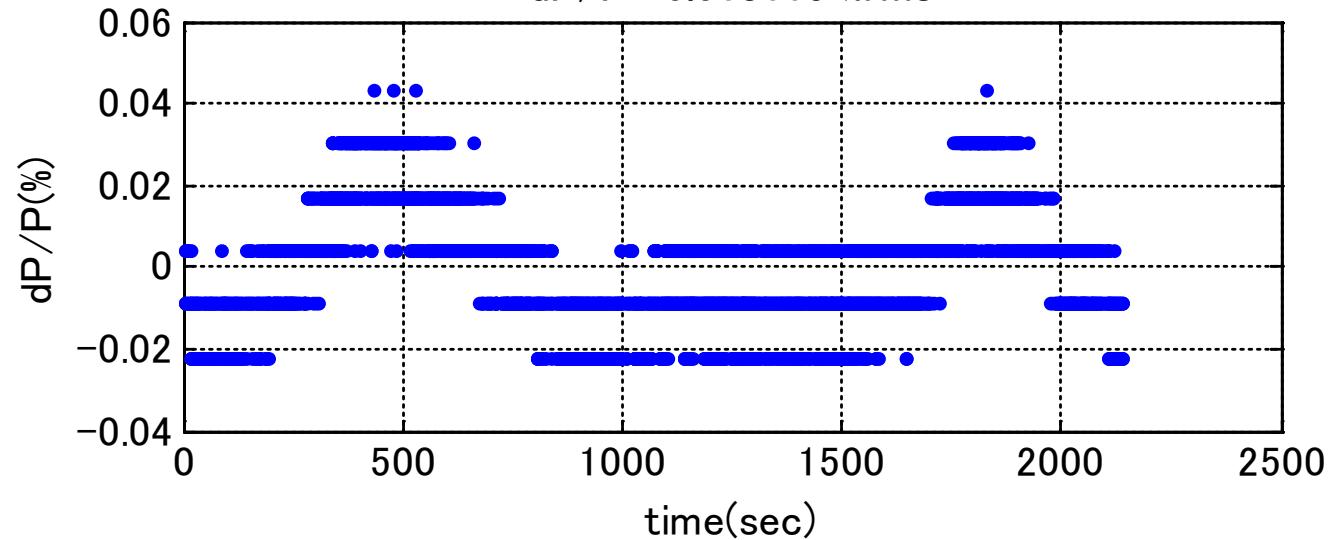
Dispersion : $\eta_x = 0.487\text{m}$

Beam: 5Hz, 3ps rms, 23 fC, total Energy=19.9 MeV

Screen Monitor

63.7 $\mu\text{m}/\text{pixel}$

$dP/P = 0.013115\% \text{rms}$



Momentum drift in the period of ~15 minutes was observed.

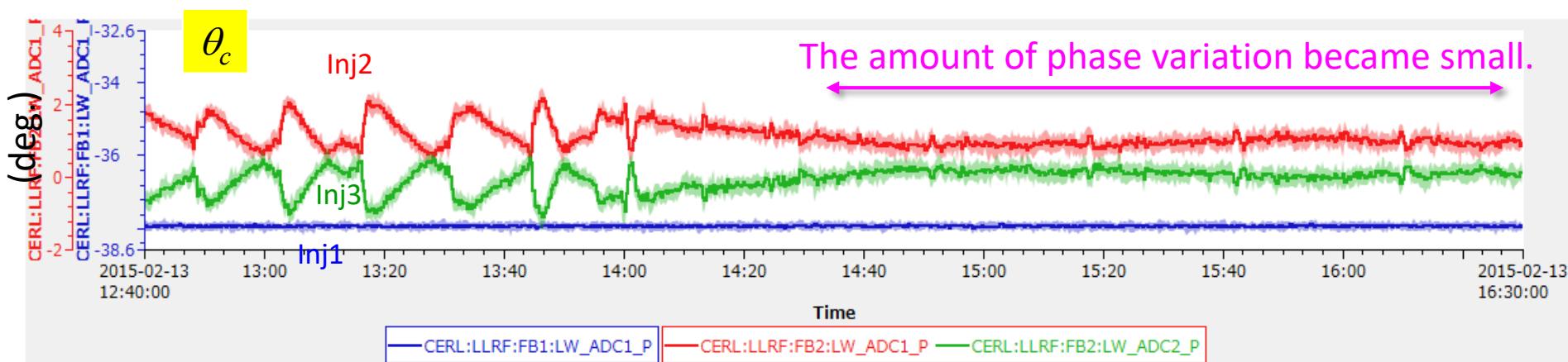
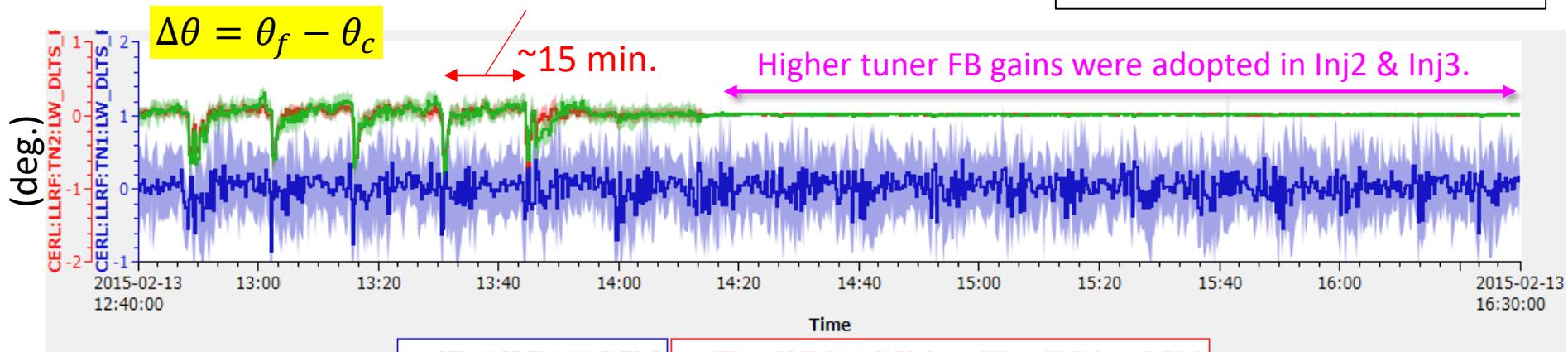


Reduction of the Effect of Vector-sum Error

$$\tan\Delta\theta \approx 2Q_L \frac{\Delta f}{f}$$

The time interval of detuning is similar to the interval of energy drift.

Blue: Inj1, Red: Inj2, Green: Inj3



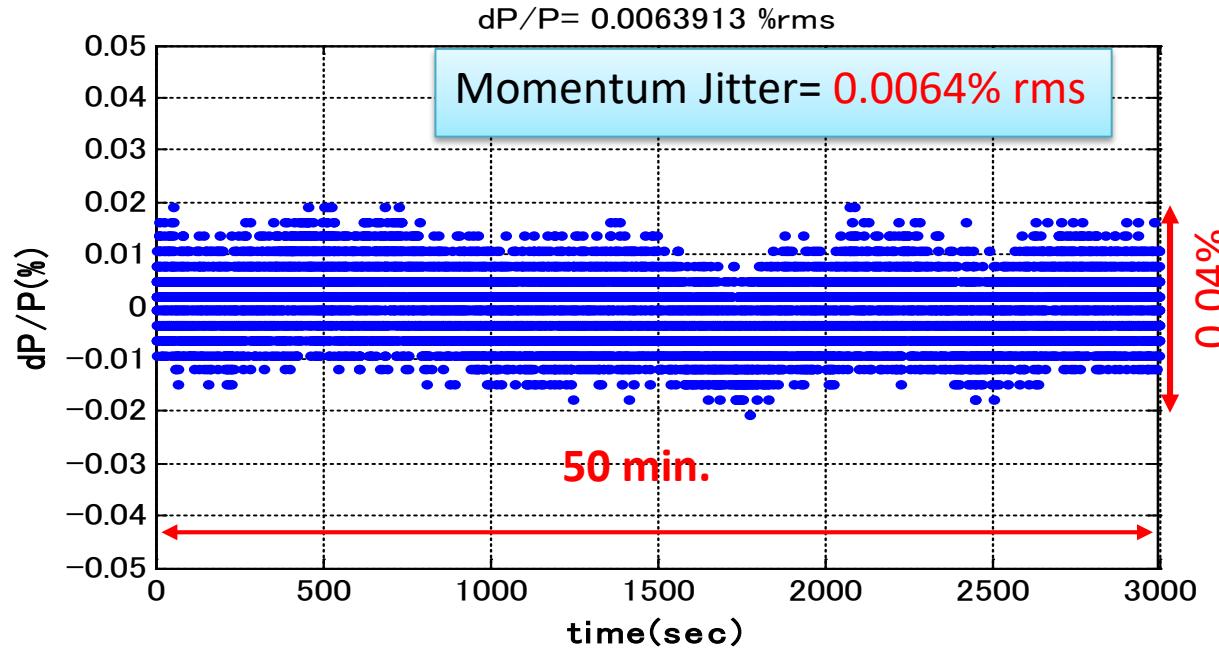
If error is included in vector-sum calibration, energy drift can occur.

In the region of Inj2 and Inj3 cavities, $\beta < 1$. Transit time is different in each cavity.
=> weight of vector-sum is different between Inj2 and Inj3.



Stability of Beam Momentum (2)

Measurement after modification of tuner feedback gain for Inj2 and Inj3



Large momentum drift disappeared.

Good stability of beam momentum was achieved.

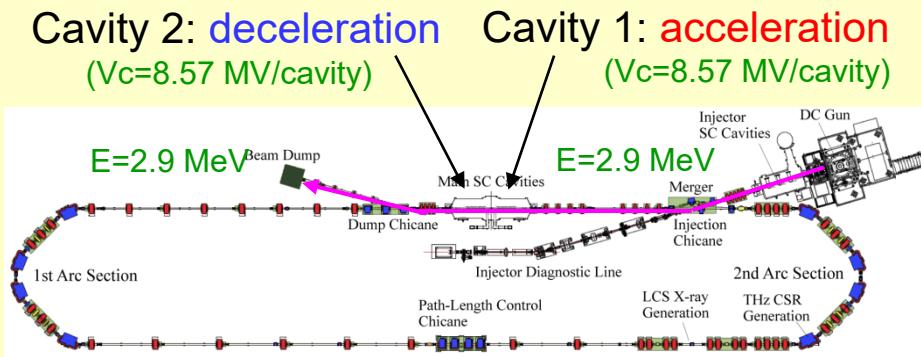
=> It was confirmed that the RF field for the beam is stable.

Demonstration of Energy Recovery ($I_0 = 30 \mu\text{A}$)



Non-ERL operation

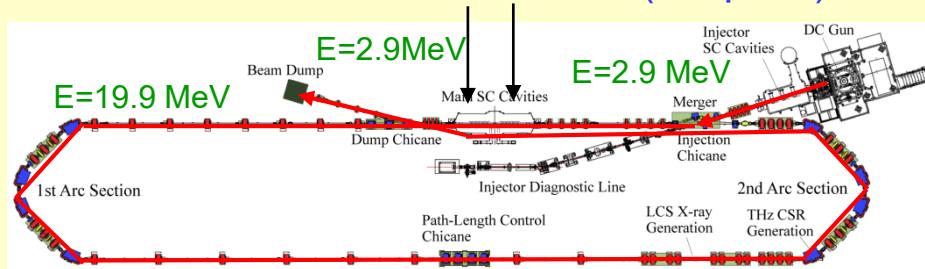
Cavity 2: deceleration ($V_c=8.57 \text{ MV/cavity}$)



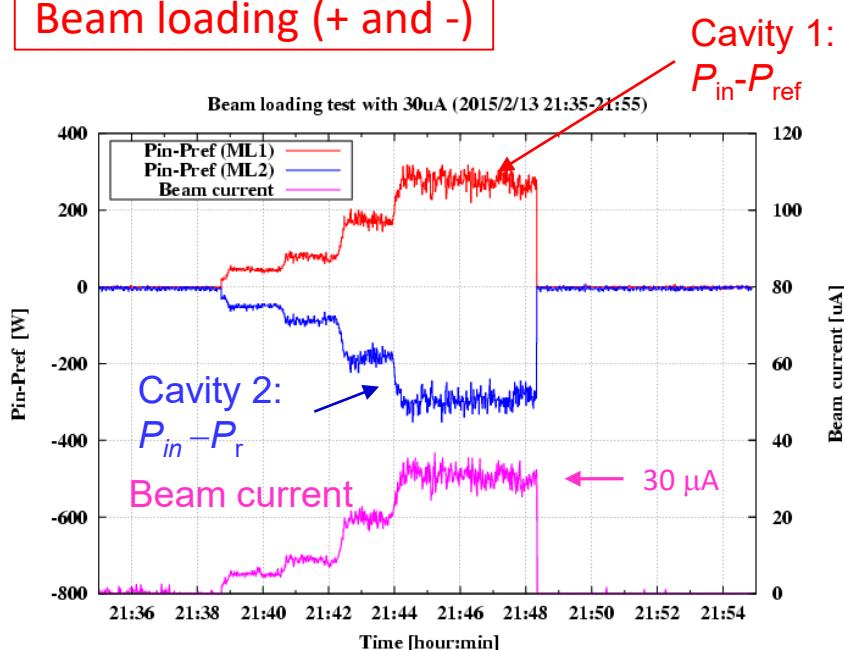
Cavity 1: acceleration ($V_c=8.57 \text{ MV/cavity}$)

ERL operation

Cavities 1 and 2: acceleration (1st pass) and deceleration (2st pass)



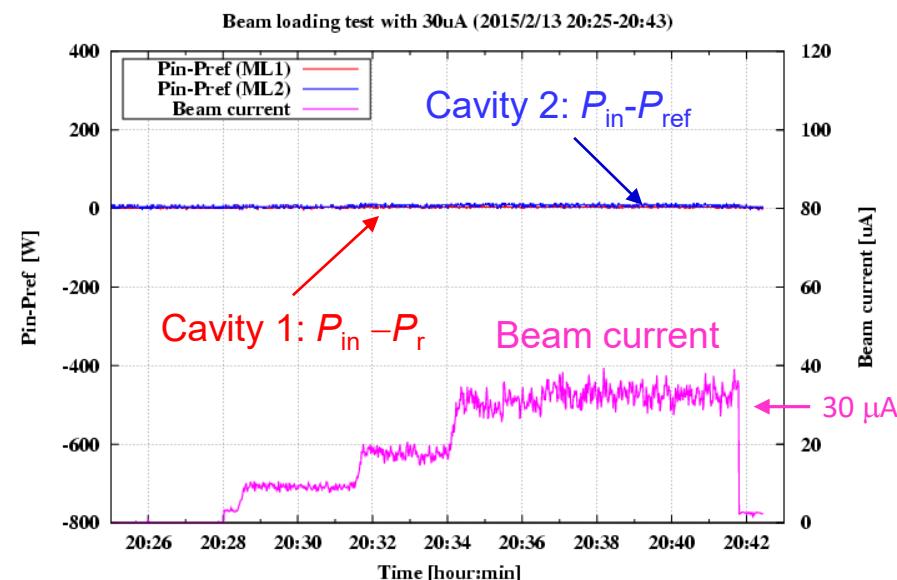
Beam loading (+ and -)



Cavity 1:
 $P_{\text{in}} - P_{\text{ref}}$

No beam loading

Energy recovery: 100-98.6%
(within accuracy of the measurement)



(Power lost in cavity) = (P_{in} : input power to cavity) - (P_{ref} : reflected power from cavity)

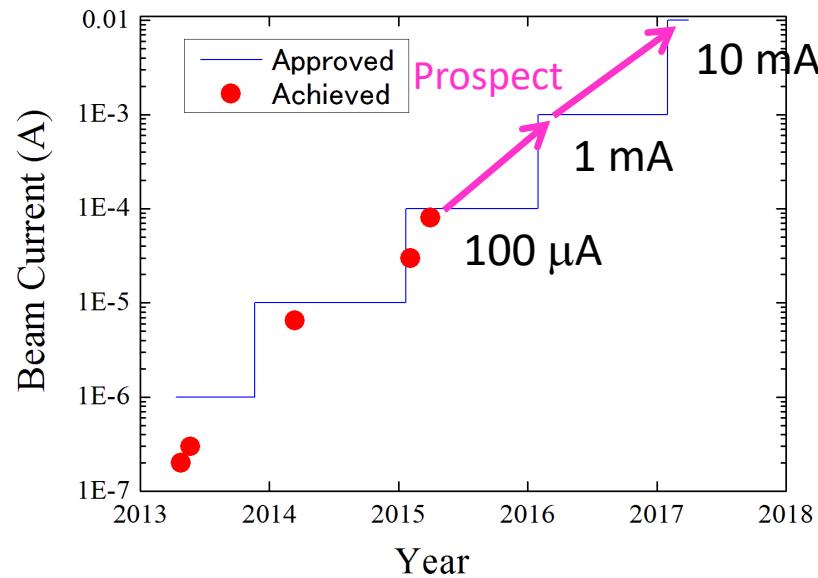


Summary

- RF stabilities satisfied the requirement for cERL, and almost satisfied the requirement for 3GeV ERL.
- The beam momentum jitter of 0.006% rms was achieved.

Future Plan

- Tuner feedback parameters have not been optimized enough.
We will optimize the tuner control parameters.
- Beam current will increase and burst mode operation is planned.
Beam loading compensation is necessary.
[Feng Qiu (KEK), this afternoon]
- The evaluation of the long-term stability is necessary.



Thank you for your attention.