

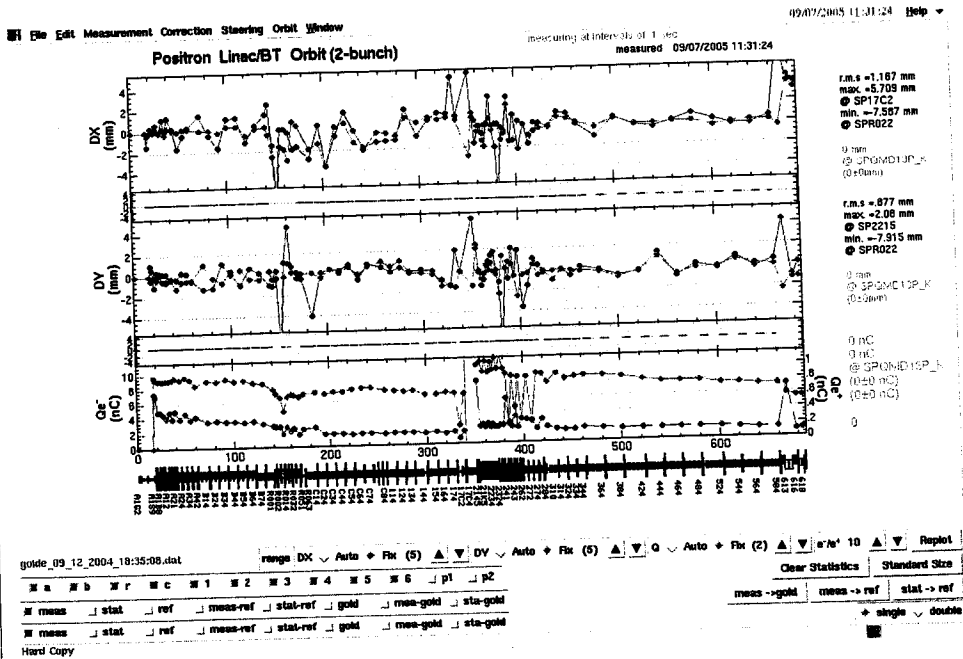


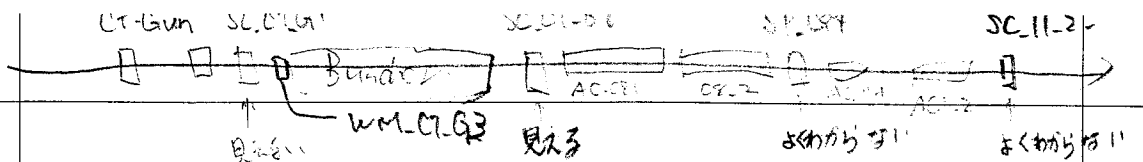
05/09/07 11:26

OK

11:34

B 79 W.S. 動作確認 ⇒ OK





13.21

BM-CT-G0 2.049 → 2.226

BMCT-G0 2.226 → 2.067 → 2.145

SY-CT-G0 -0.6A → -0.602

Linac / BTe Orbital CT 以降 7" - 7" 変化したくない。 RAS Reset IB. 1B. 12E 様子が変わす

Beam sync Panel ~ PF 同期はずれ 全KLY Down.

BM-CT-G0 2.070 → 2.145

SY-CT-G5 -0.000 → -0.040 (元)

KL-CT Phs 361.8 → 217.0°

~~CT-G00 Delay~~

KL-CT Timing 14524 → 14924

BM-CT-G0 2.079 → $\frac{2.067}{1}$

SPC84 δ^{max} MAX.

WM-CT-G8 変化した ① KL-CT Phase. ⇒ 元値.

BM-CT-G0 2.067 → 2.096

FC-CT-G123 12.005 → 9.605

BM-CT-G0 2.096 → 2.145

FC-CT-G1/2/3 9.607

FC-CT-G4/5/6 11.009 → π

FC-CT-G7/8 ~~9.26~~ 9.265 → 9.863

FC-CT-P1/2 19.906 → π

FC-CT-B1/2 19.017 → π

FC-CT-B3/4/5 19.923 → π

FC-CT-B7/8/9 29.085 → π

{ BM-CT-G0 2.145 → 2.082

FC-CT-G1/2/3 9.607 → π

ML-CT-G 2.668 → 1.868

SC-26_3 SC ~~of 118~~ → KL-26 E_s → ~~32.01~~ 39.0KL

KL-CT Phase 216.5 → 226.5

FC-CT-G1/2/3 9.607 → 8.807

SX-CT-G0 0.001 → -0.399

SY-CT-G0 -0.602 → -0.802

SX-CT-G5 0.040 → 0.140

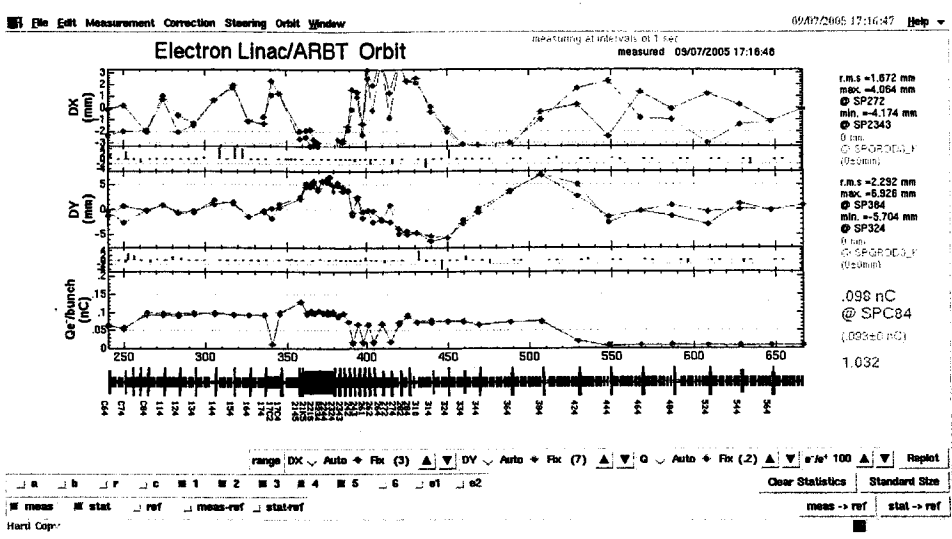
SY-CT-G5 -0.043 → π

ML-CT-G 1.868 → 1.848

BM-CT-G0 2.082 → π

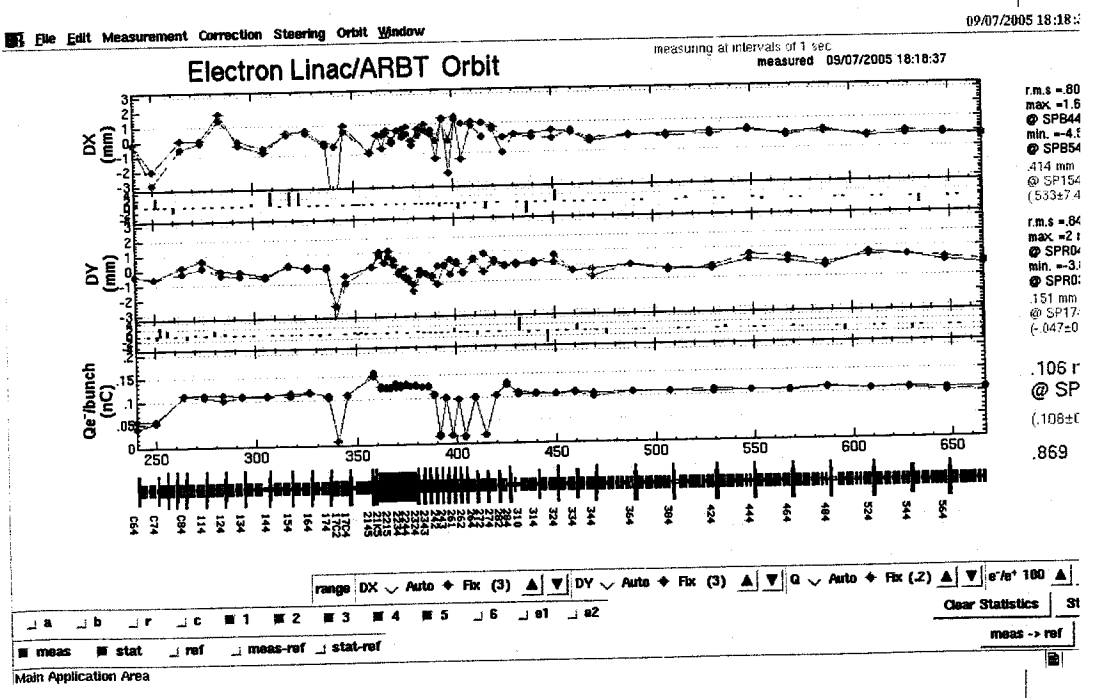
KL - CT Es 31.0kV → 31.5kV

KL - CT Phase 226.4 → 224.4



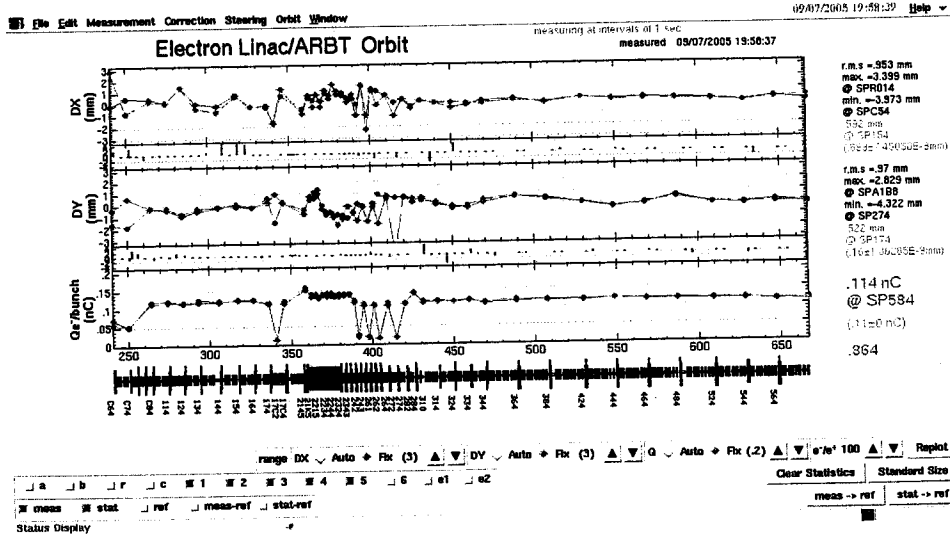
17:21

AR beam 110³/₂

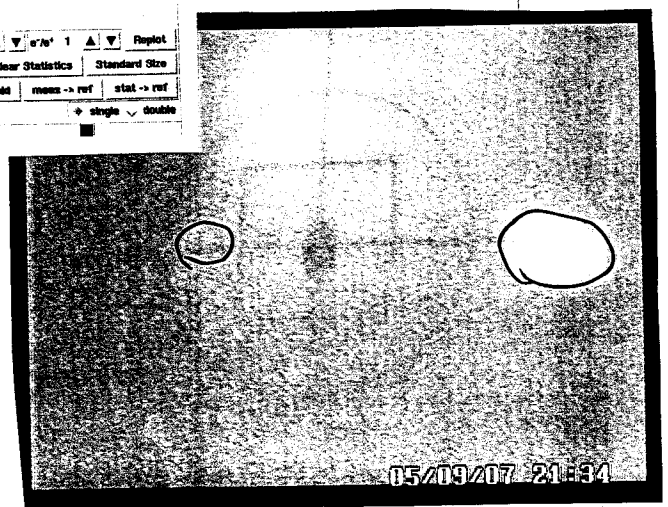
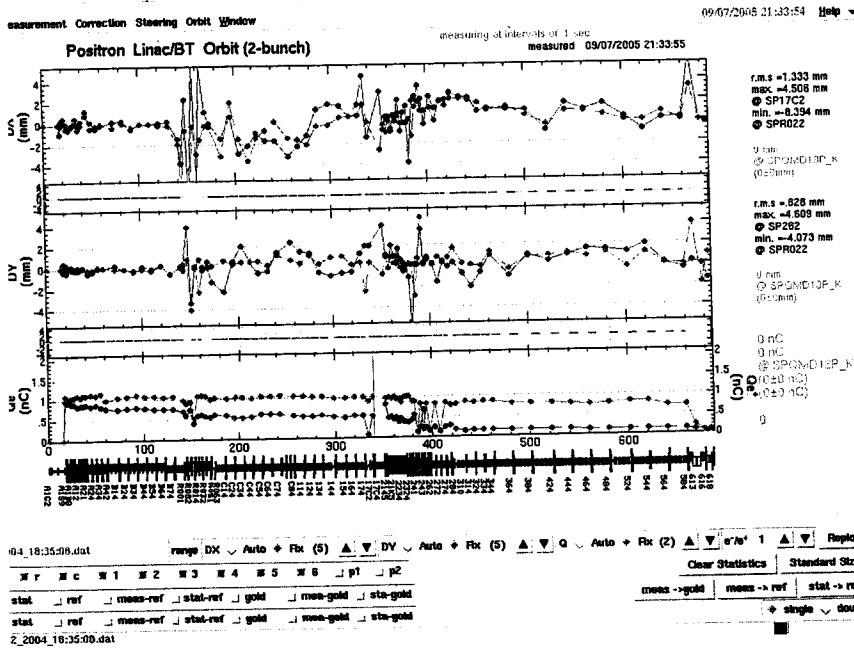


19258

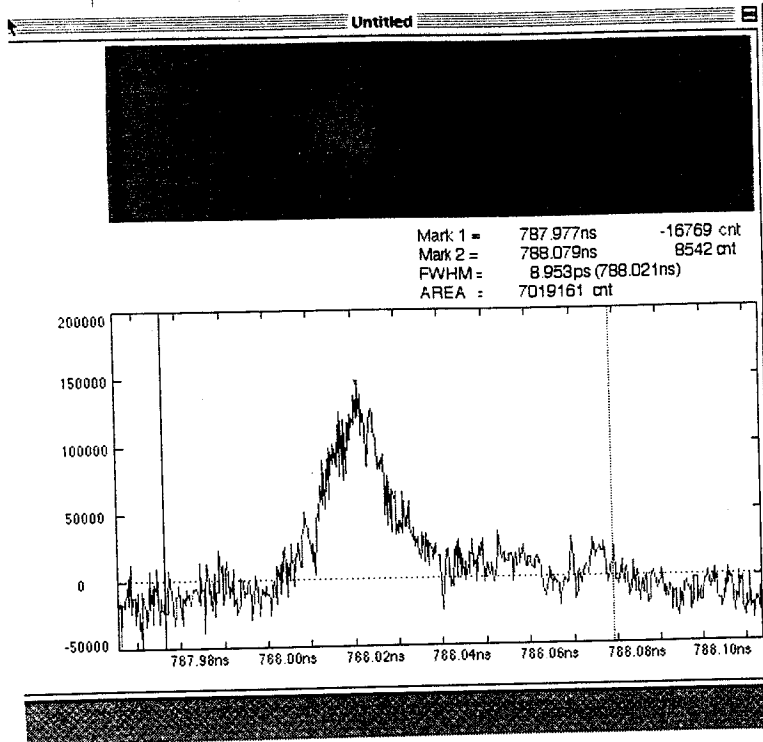
PT Beam 調整



KEKB e⁻ 2 bunch 調整



e⁺ 2ハズリ



Measurement Condition

Live Time pulse
 Accum.Time pulse

Control the Streak Camera
 H-Sweep Range

MCP Gain %
 Delay ns
 Search pulse : cnt.

Input Optics
 Focus : open
 Slit Width : um

Gravity Integ. Trig.Single

Table... Quit Do It

Gallery

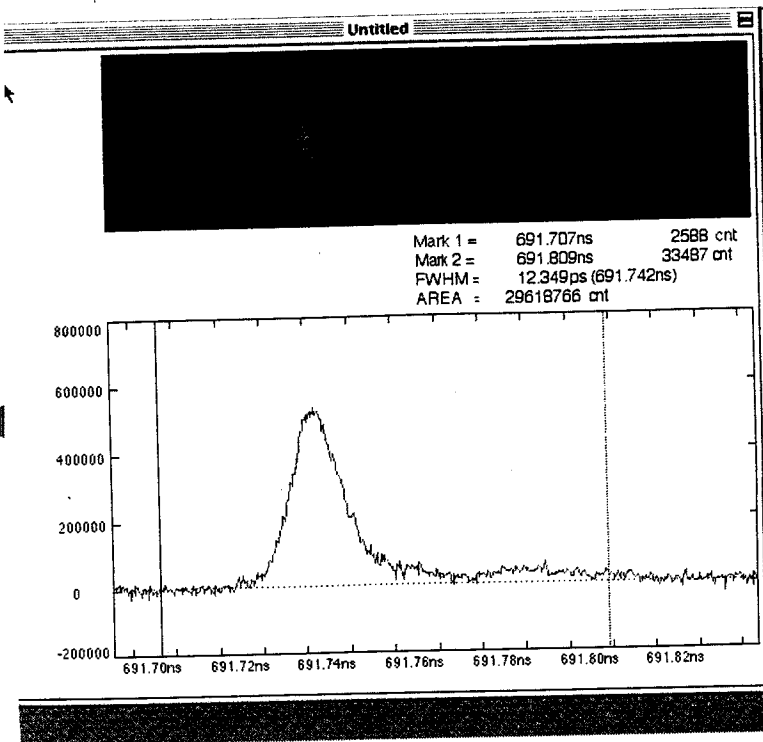
Left
 Down
 Near
 Tunnel
 Left
 Down
 Near

Filter Bandp
 Filter... Load
 Quit Load

Image Status

<< Condition : BeamC6699_R1 >>
 Accum.Time 50 pulse
 Mcp Gain 100[%]
 Streak Mode 8.20[NS]
 Streak Trigger SINGL
 H:-0.240 V: 0.120 Z: 7.1840
 DC Calibration ON
 DATE 2005:09:17
 TIME 22:21:4 J
 << Comment >>
 (Bandpass 1)

e⁺ 1ハズリ



Measurement Condition

Live Time pulse
 Accum.Time pulse

Control the Streak Camera
 H-Sweep Range

MCP Gain %
 Delay ns
 Search pulse : cnt.

Input Optics
 Focus : open
 Slit Width : um

Gravity Integ. Trig.Single

Table... Quit Do It

Gallery

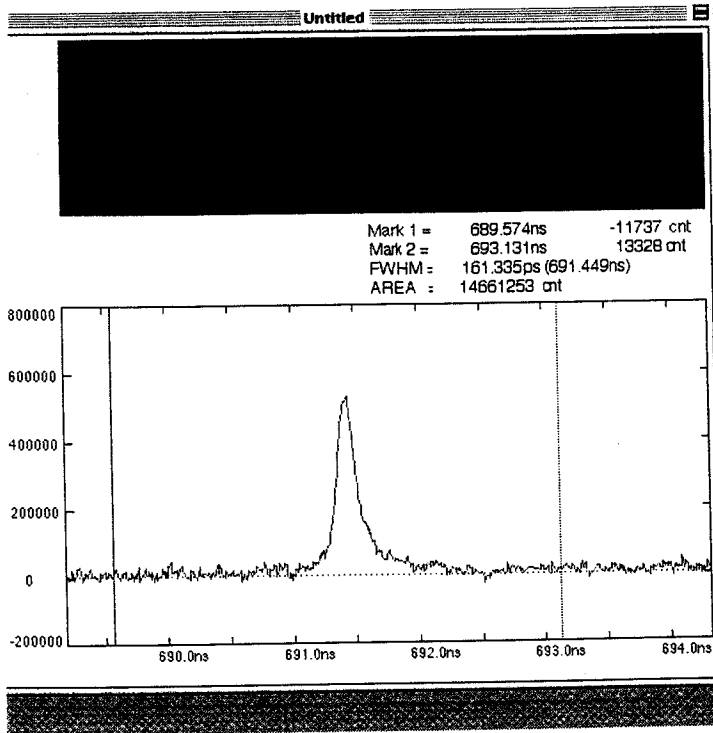
Left
 Down
 Near
 Tunnel
 Left
 Down
 Near

Filter Bandp
 Filter... Load
 Quit Load

Image Status

<< Condition : BeamC6699_R1 >>
 Accum.Time 50 pulse
 Mcp Gain 100[%]
 Streak Mode 8.20[NS]
 Streak Trigger SINGLE
 H:-0.240 V: 0.120 Z: 7.1840
 DC Calibration ON
 DATE 2005:09:07
 TIME 22:24:34
 << Comment >>
 (Bandpass 1)

e+ 1A27



Measurement Condition

Live Time: 10 pulse
 Accum.Time: 50 pulse

Control the Streak Camera
 U-Sweep Range: 5ns

MCP Gain: 79 %
 Delay: 536.83 ns

Search pulse: 5000 cnt.

Input Optics
 Focus: Open
 Slit Width: 100 um

Gravity Integ. Trig.Single

Table... Quit Do It

Optics_A1

Gallery
 Left: -0.240 mm Right
 Down: 0.120 mm Top
 Near: 7.184 mm Far

Tunnel
 Left: 6.526 mm Right
 Down: -1.978 mm Top
 Near: -4.390 mm Far

Filter: Bandpass 1

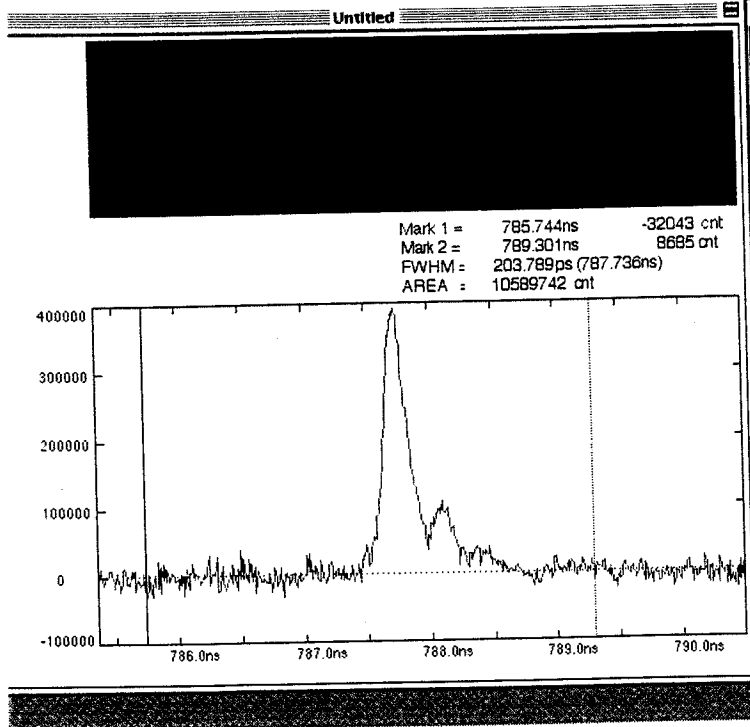
Filter... Load from... Save as...
 Quit Load Def. Save Def.

インターネットを始める
 Timbuktu Sender

Image Status

<< Condition: BeamC6699_A1 >>
 Accum.Time 58 pulse
 Mcp Gain 79[%]
 Streak Mode S[NS]
 Streak Trigger SINGLE
 H:-0.240 V:0.120 Z:7.1840
 DC Calibration ON
 DATE 2005:09:07
 TIME 22:26:17
 << Comment >>
 [Bandpass 1]

e+ 2A27



Measurement Condition

Live Time: 10 pulse
 Accum.Time: 50 pulse

Control the Streak Camera
 U-Sweep Range: 5ns

MCP Gain: 100 %
 Delay: 633 ns

Search pulse: 5000 cnt.

Input Optics
 Focus: Close
 Slit Width: 100 um

Gravity Integ. Trig.Single

Table... Quit Do It

Optics_A1

Gallery
 Left: -0.240 mm Right
 Down: 0.120 mm Top
 Near: 7.184 mm Far

Tunnel
 Left: 6.526 mm Right
 Down: -1.978 mm Top
 Near: -4.390 mm Far

Filter: Bandpass 1

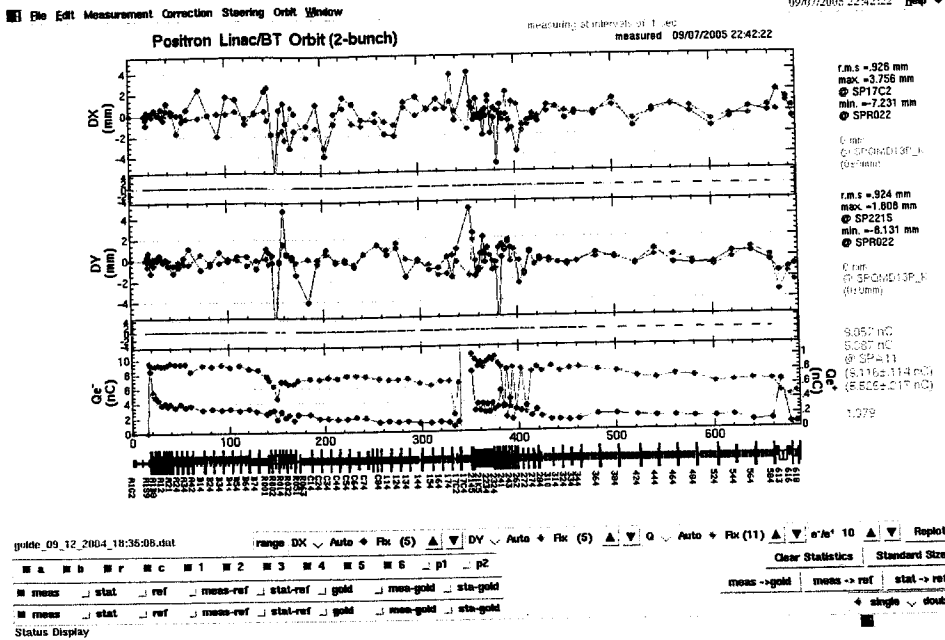
Filter... Load from... Save as...
 Quit Load Def. Save Def.

インターネットを始める
 Timbuktu Sender

Image Status

<< Condition: BeamC6699_A1 >>
 Accum.Time 58 pulse
 Mcp Gain 100[%]
 Streak Mode S[NS]
 Streak Trigger SINGLE
 H:-0.240 V:0.120 Z:7.1840
 DC Calibration ON
 DATE 2005:09:07
 TIME 22:29:06
 << Comment >>
 [Bandpass 1]

e+ 2バッチ

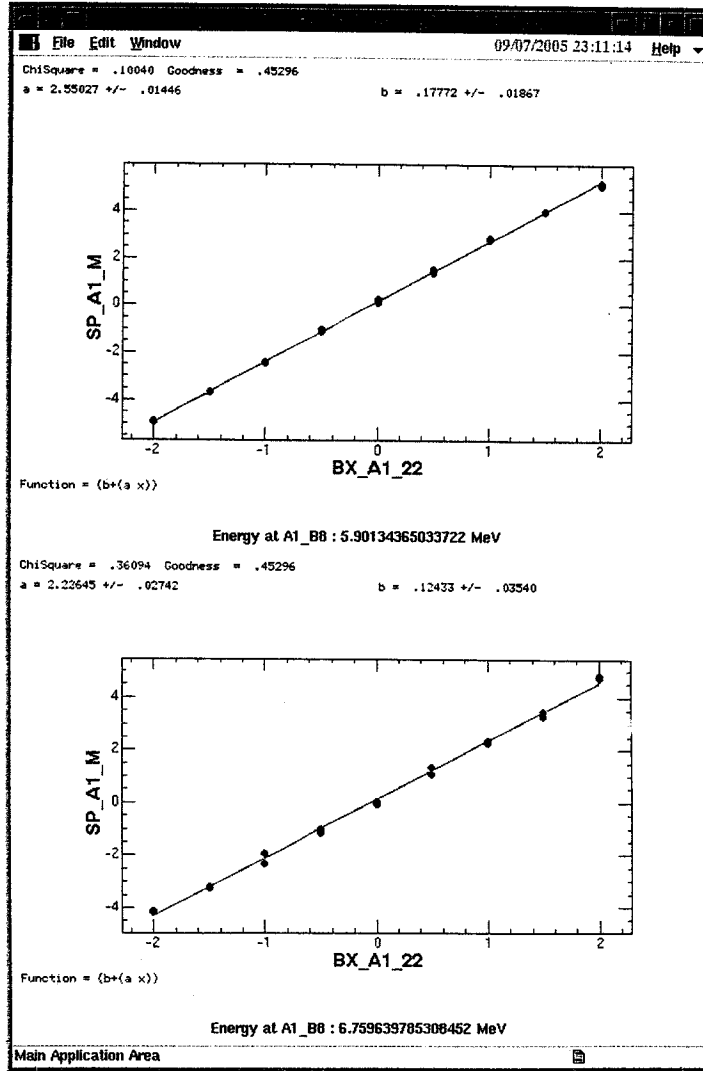


2バッチ目が大きくD2になる
 AIの最初の軌道修正あり。

⇒ AI-REFの timing を動かすとすると、軌道修正が
 (エラー修正の要はなしと想定)

[矢野氏にX-H-Z 同位合わせ中]

e⁺ 2bunch

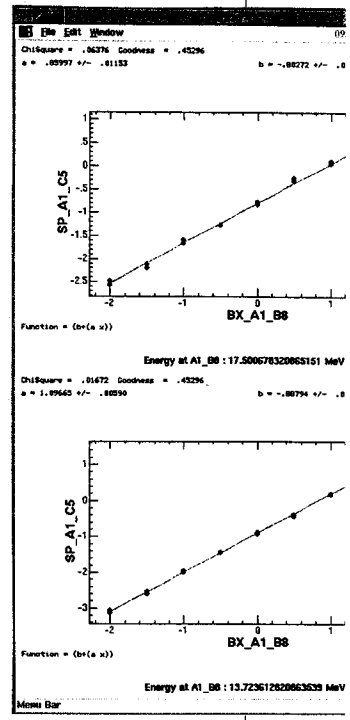
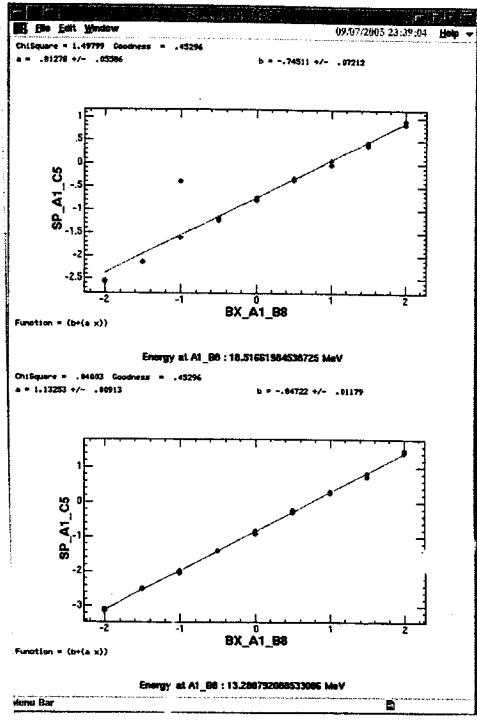
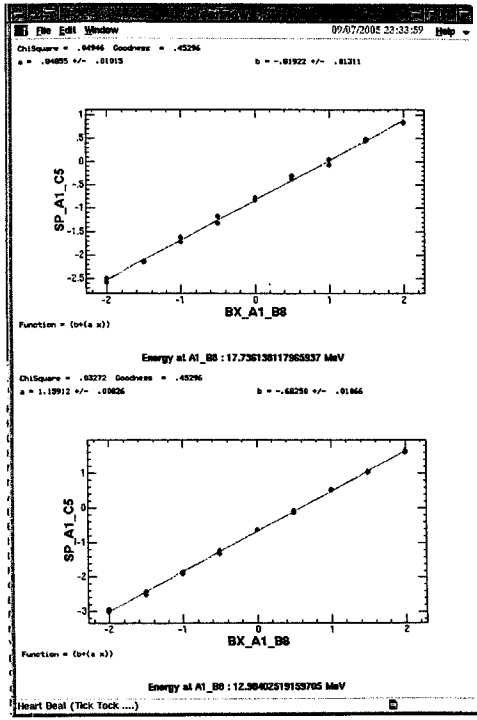


e+

Delay2 = 2.200

2.250

2.300



2.350

2.400

2.450

